

ANESTHESIA  
TECHNOLOGY  
ULTRASOUND PHYSICS

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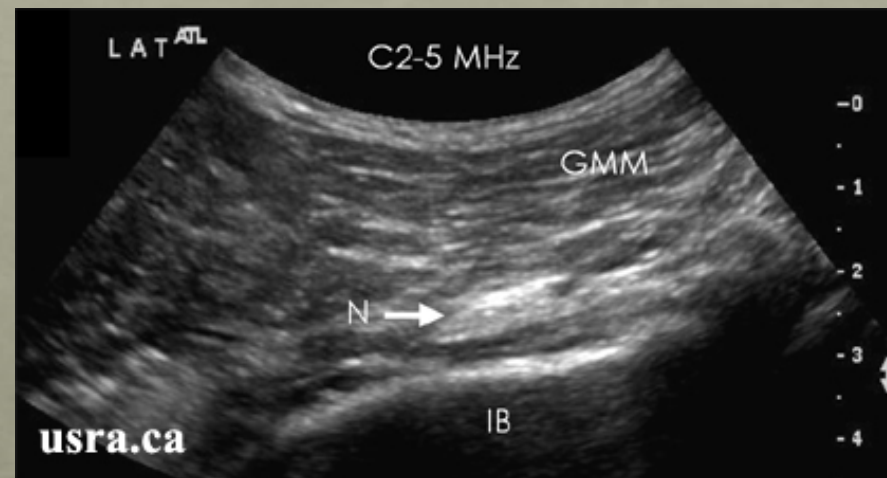
# OBJECTIVES

## Ultrasound Physics

- Physics
- Probe Orientation
- Descriptive Terms
- Knobology
- Optimization
  - Patient positioning
  - Ultrasound

# ULTRASOUND GUIDED

- Real Time
- Anatomy aware
- Aberrancy appreciated
- Local Distribution
- Identify non-motor nerves (saphenous, TAP)



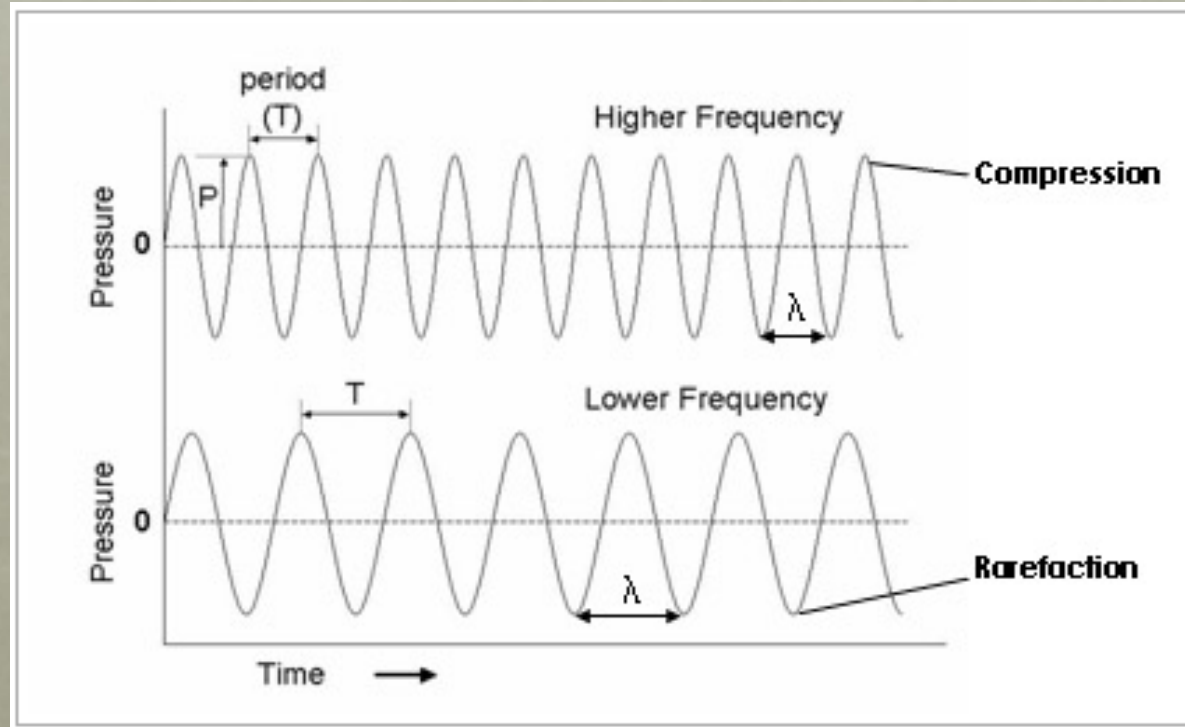
# ULTRASOUND PHYSICS

SEEING WITH SOUND

## Basic Principles:

Ultrasound is form of mechanical sound energy that travels through a conducting medium (e.g., tissue) and then gets reflected back to form an image.

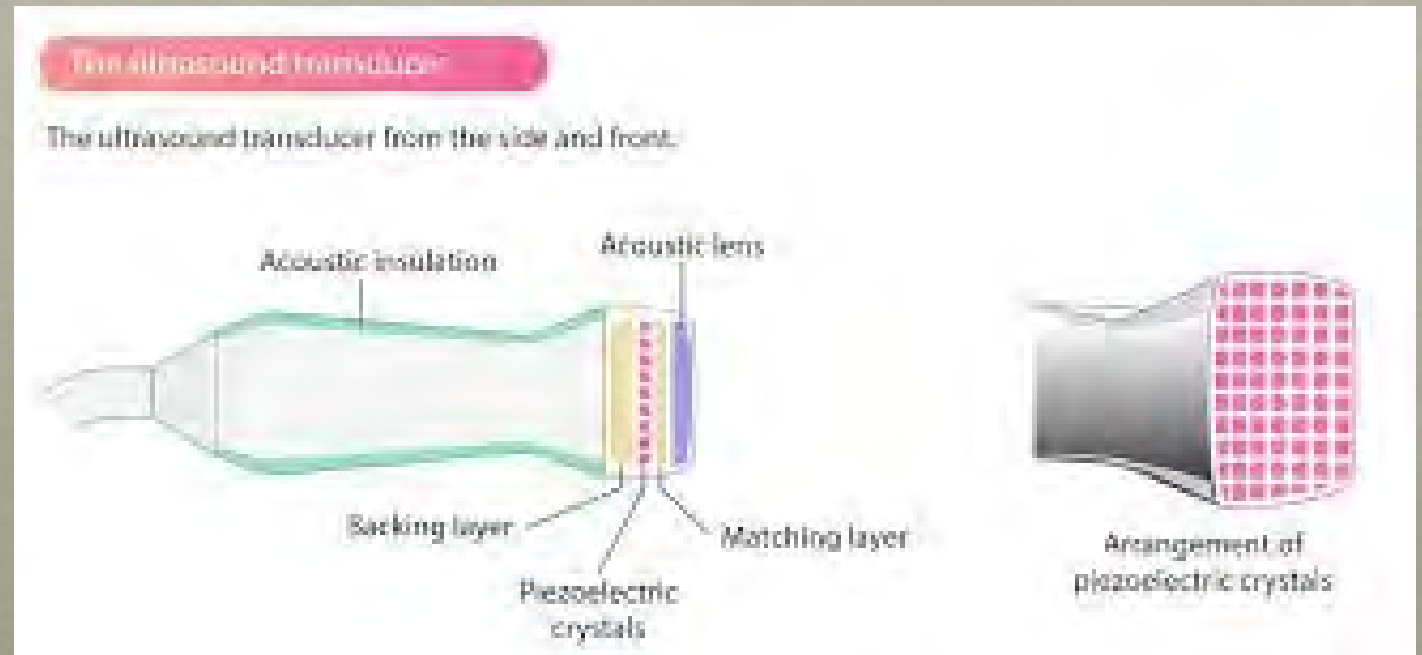
# ULTRASOUND PHYSICS

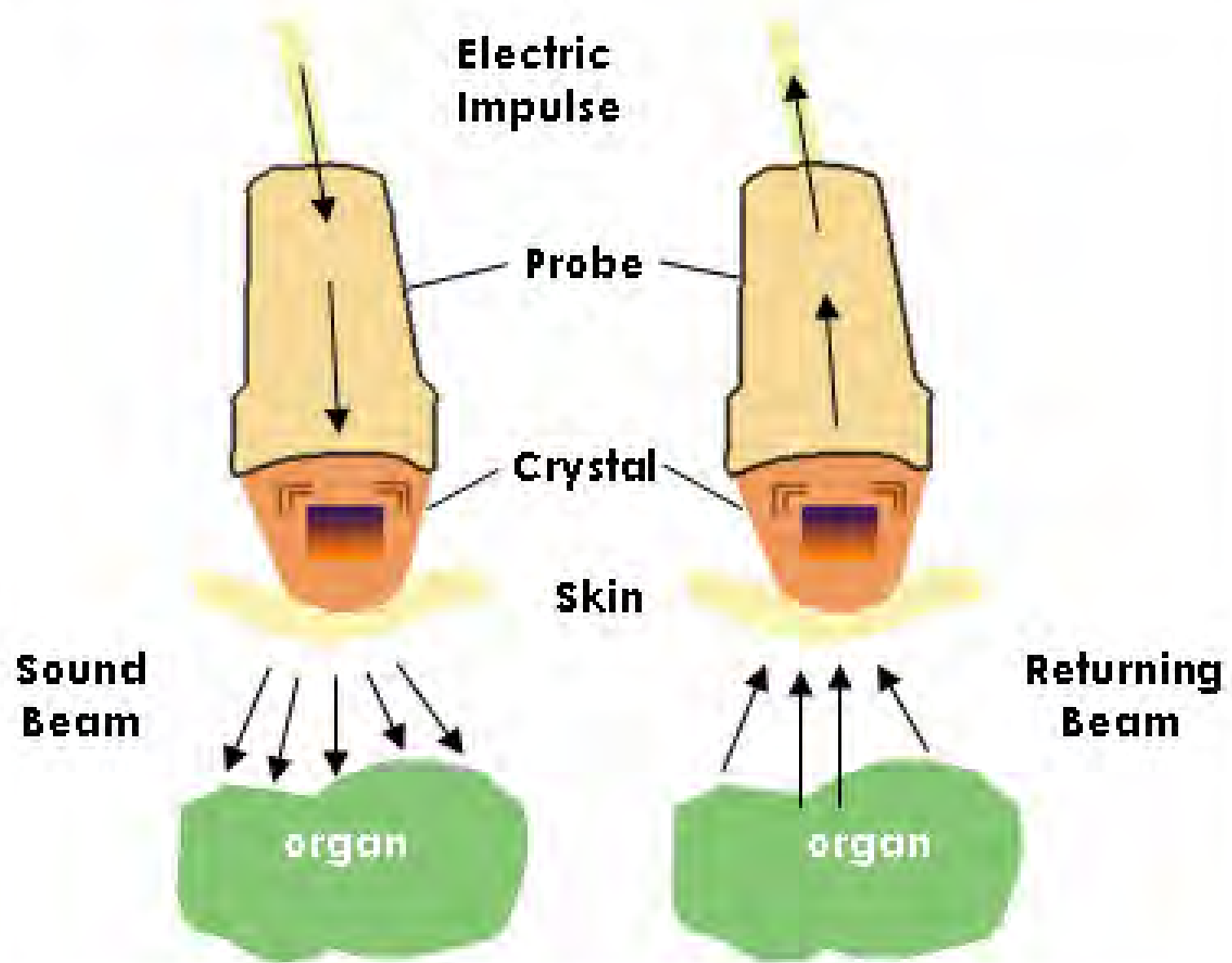


- A sound sinusoidal waveform
- Characteristic
  - Pressure, wavelength, frequency, and velocity

# ULTRASOUND PHYSICS

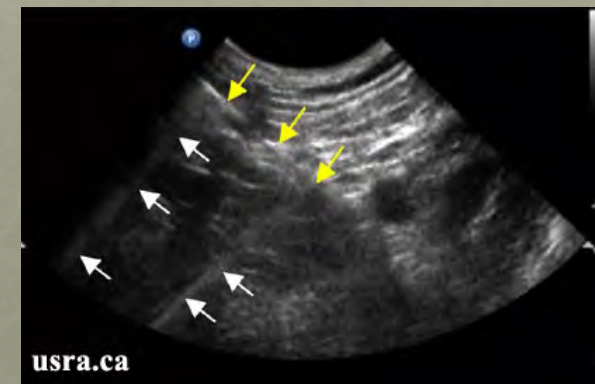
- Electrical energy gets transmitted to piezoelectric crystals that forms the ultrasound wave.
- Waves are generated in pulses











# ULTRASOUND PHYSICS

- As the ultrasound beam travels through tissue layers, the amplitude of the original signal becomes attenuated as the depth of penetration increases. **Attenuation** (energy loss) is due to:
  - Absorption
  - Reflection
  - Scattering
- High frequency is associated with high attenuation – therefore, limited tissue penetrations.
  - High freq for superficial structures.
  - Increased resolution.
- Low frequency
  - Deep structures.





# ULTRASOUND PROBES

Appearance	Type	Depth (cm)	Description and use cases
	Linear array 7-15 MHz	2-7	Very high spatial resolution but limited penetration. Creates a rectangular field of view with less artifact compared to convex arrays. Typically large foot-print so limited to large craniotomies.
	Convex array 2-10 MHz	10-30	High spatial resolution with good penetration. Fan shaped large field of view. Large foot-print so limited to large craniotomies.
	Micro-convex 4-13 MHz	6-10	High spatial resolution with good penetration. Fan shaped large field of view. Smaller foot-print so more adaptable and usable in smaller craniotomies with potential for intracavitary use depending on resection size.
	Sector array 4-10 MHz	4-8	Small foot-print. Produces trapezoid image allowing wide field of view from a small craniotomy. Resolution lower at depth. Can be used for burr-hole guided surgery for instance for VP shunt placement.
	Matrix phased array 1-8 MHz	5-20	Type of sector array and often used in neurosurgery. Allows direct easy acquisition of a pyramidal 3D US image allowing volumetric reconstruction in any axis and facilitating visualization of adjacent structures. Produces relatively large field of view but resolution and contrast between different structures is poorer versus linear and convex array probes.
	Small linear "Hockey-stick" 6-15 MHz	2-5	Small foot-print, very high resolution but limited penetration. Can be placed directly into the resection cavity for high resolution assessment of superficial residual disease at the resection margin.

# ULTRASOUND PROBES



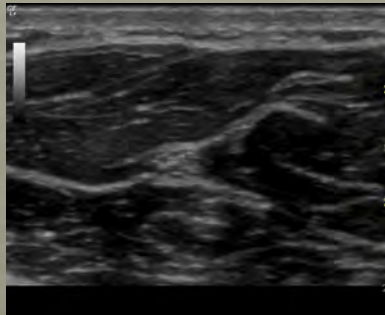
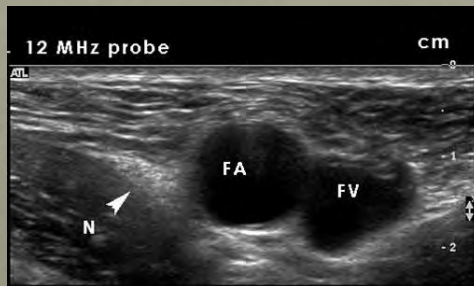
Linear



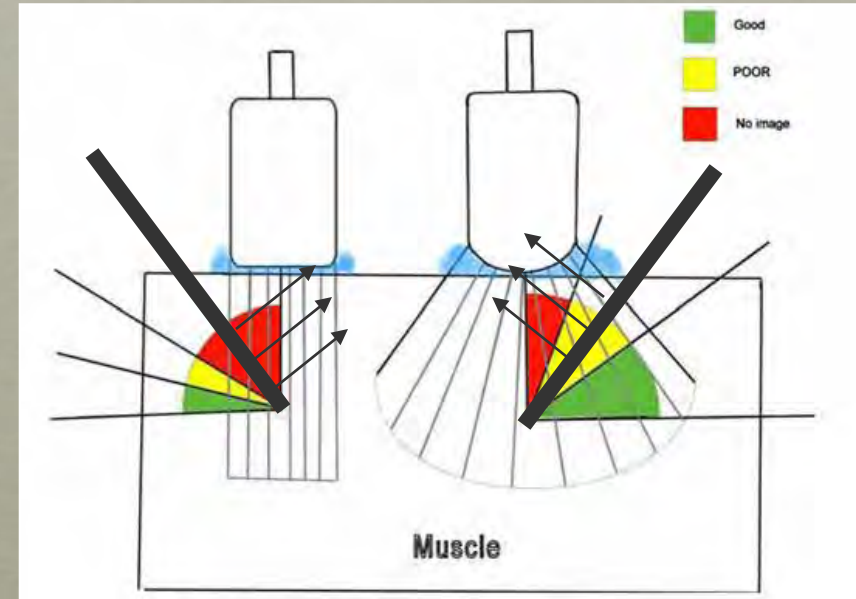
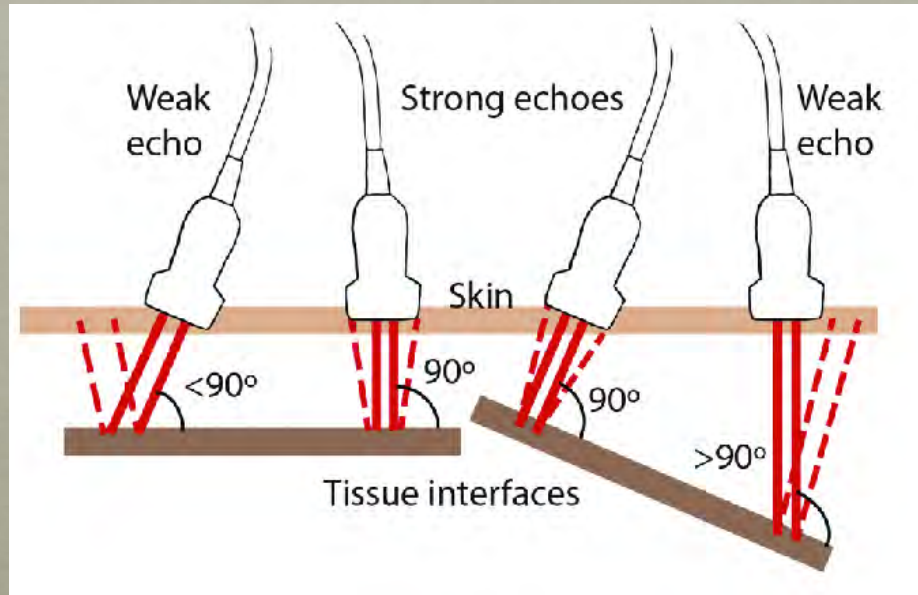
Hockey Stick Linear



Curved Array



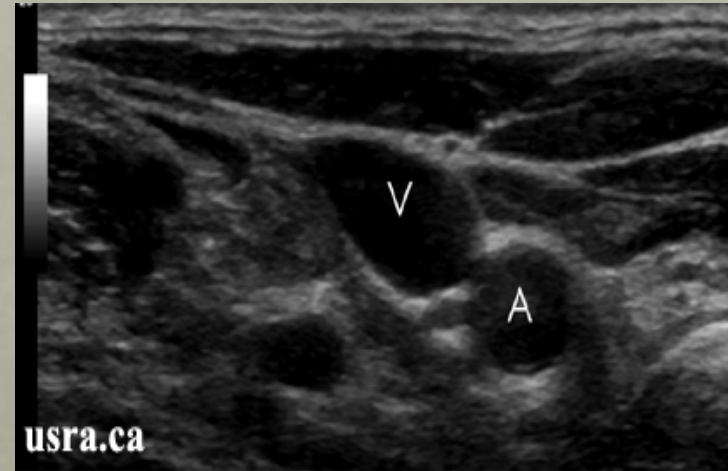
# PROBES AND THE ANGLE OF INCIDENCE



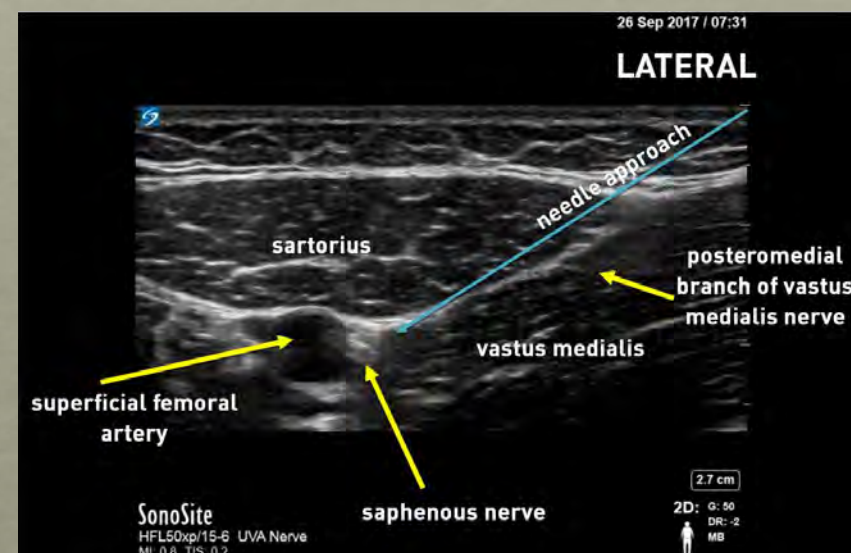
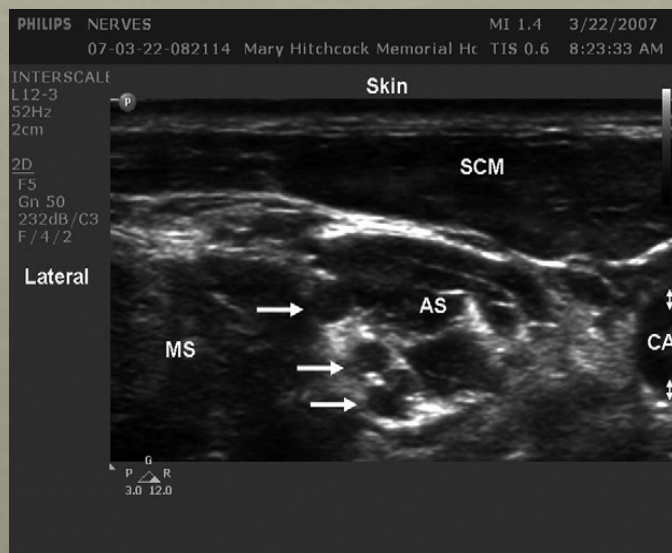
**Angle of insonation is defined as the angle of the ultrasound beam relative to the tissue or organ of interest. The strongest echoes are produced when the angles of incidence approach the angle of reflection.**

# IMAGING

- Structures that allow for sound wave transmission cause no reflection = BLACK (Anechoic)
- Little to no transmission cause reflection = White (Hyperechoic)

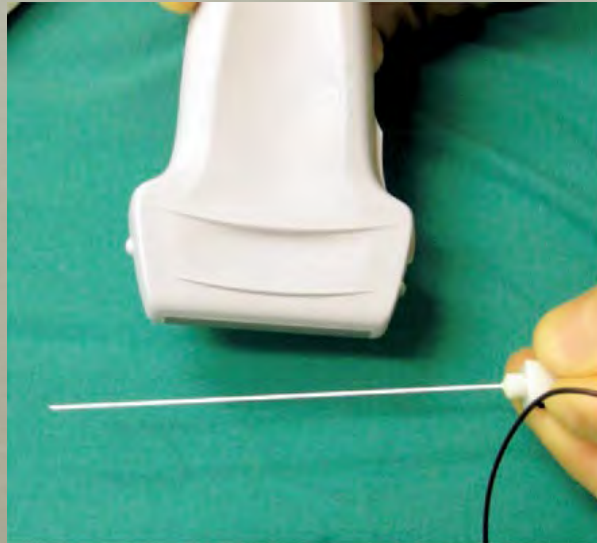


TISSUE	ULTRASOUND IMAGE FOR REGIONAL ANESTHESIA
Veins	anechoic (compressible)
Arteries	anechoic (pulsatile)
Fat	hypoechoic with irregular hyperechoic lines
Muscles	heterogeneous (mixture of hyperechoic lines within a hypoechoic tissue background)
Tendons	predominantly hyperechoic technical artifact (hypoechoic)
Bone	++ hyperechoic lines with a hypoechoic shadow
Nerves	hyperechoic / hypoechoic technical artifact (hypoechoic)



# ORIENTATION

Long Axis

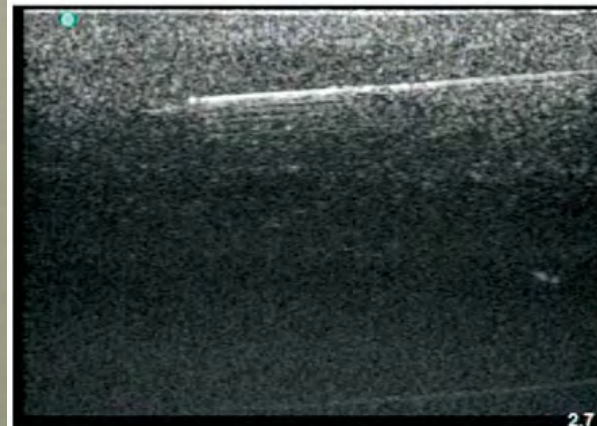


**A**



**C**

Short Axis



**B**



**D**

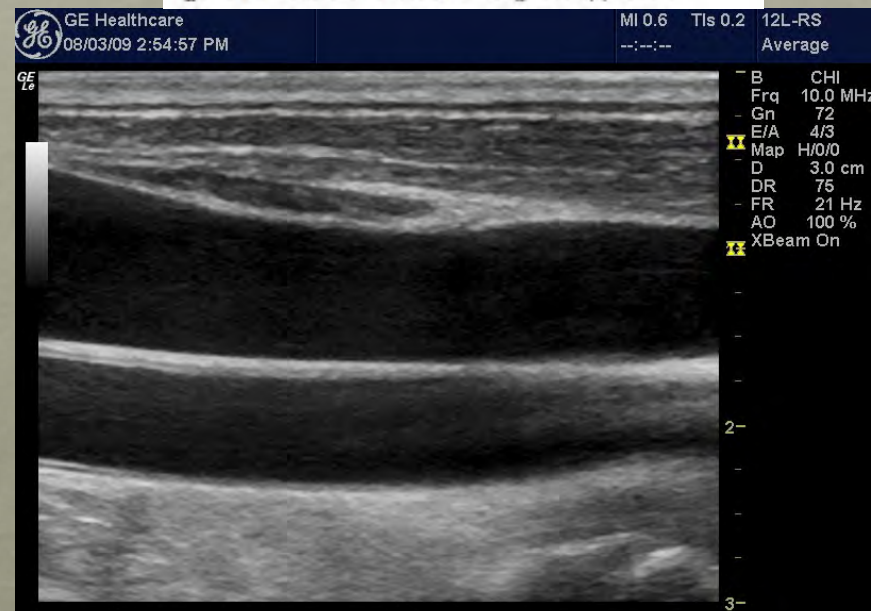
# SHORT AND LONG AXIS



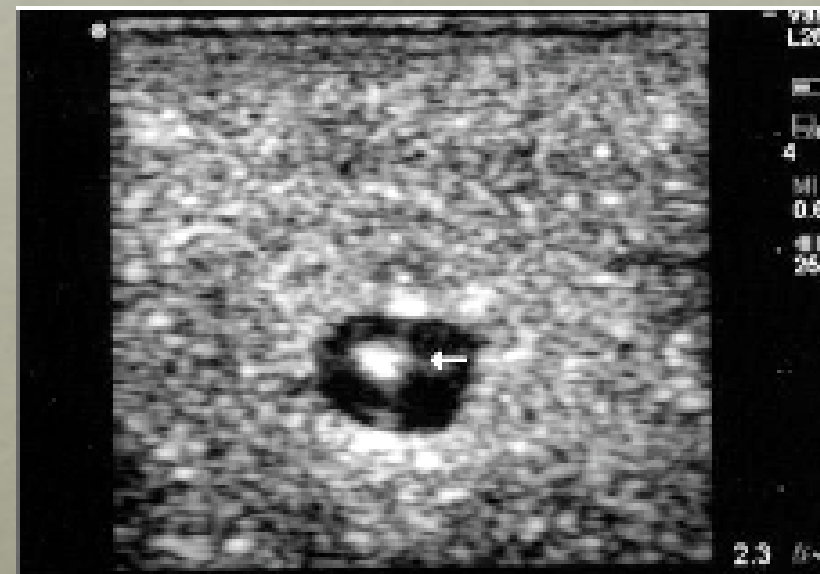
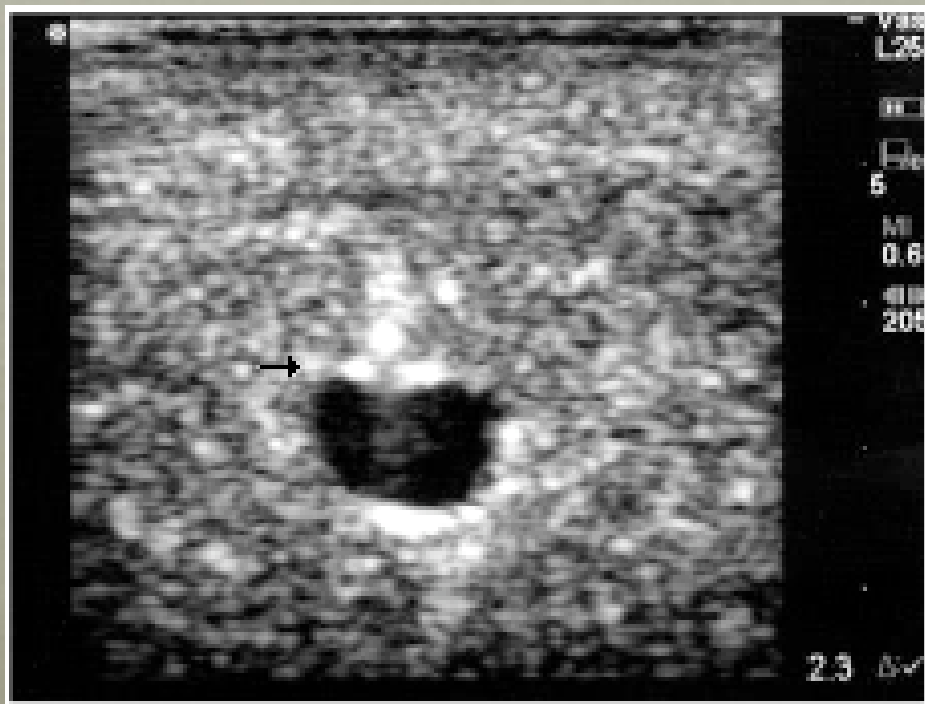
Figure 5. Needle orientation in short-axis approach.



Figure 9. Needle orientation in long-axis approach.

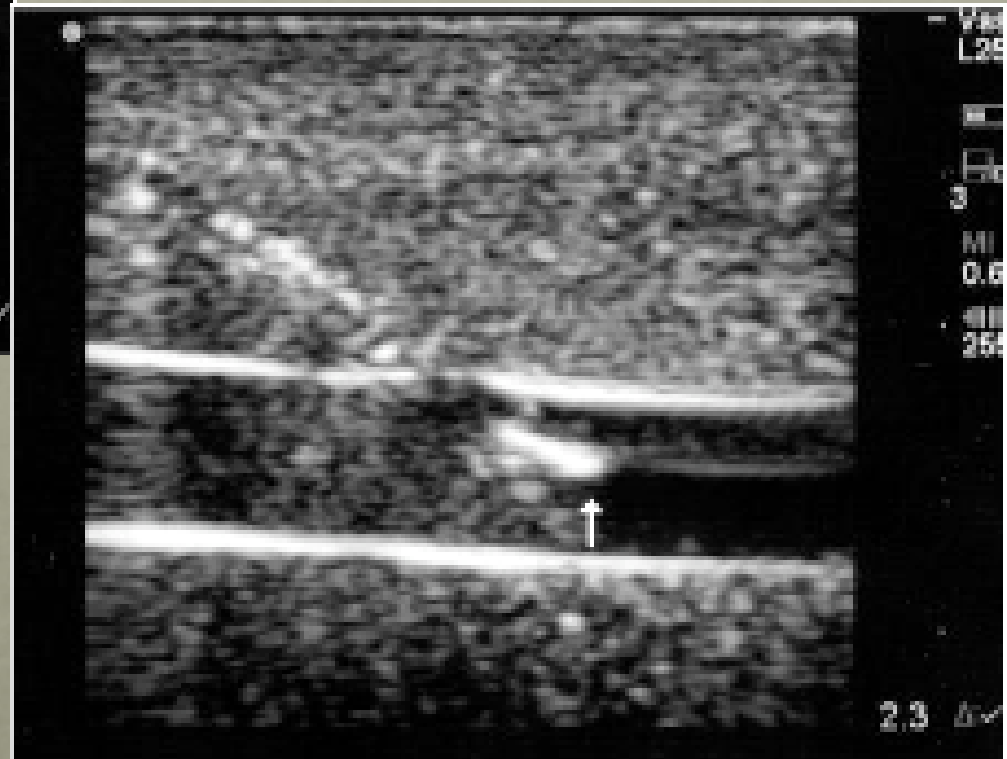
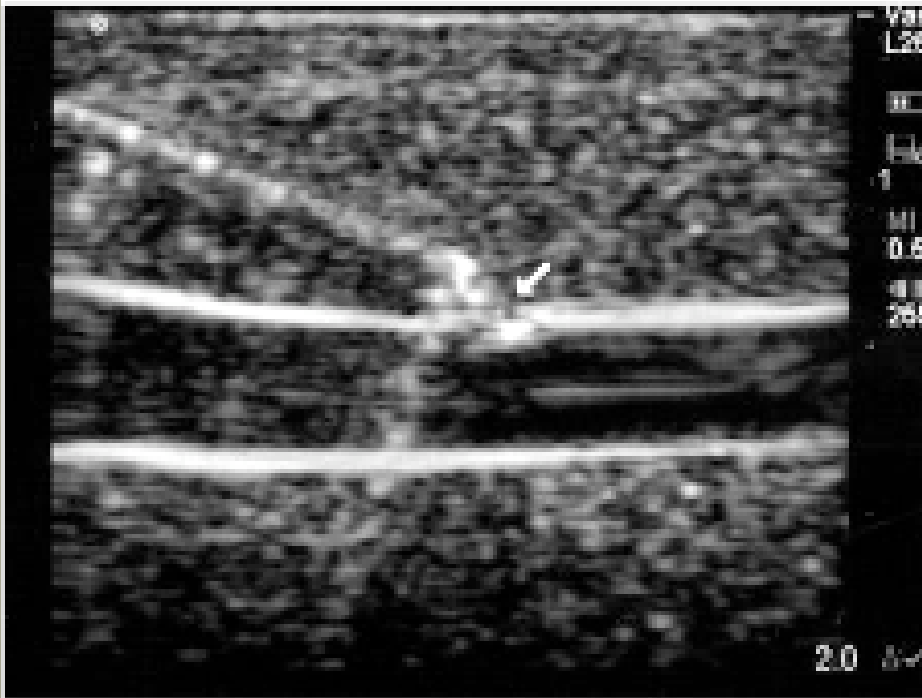


# SHORT AXIS

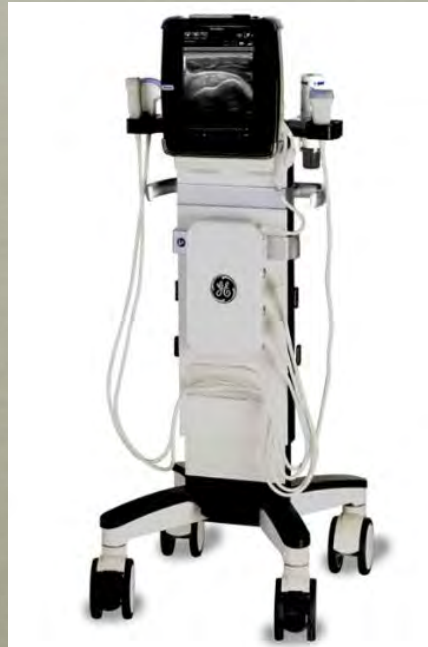




# LONG AXIS



# ULTRASOUND MACHINES

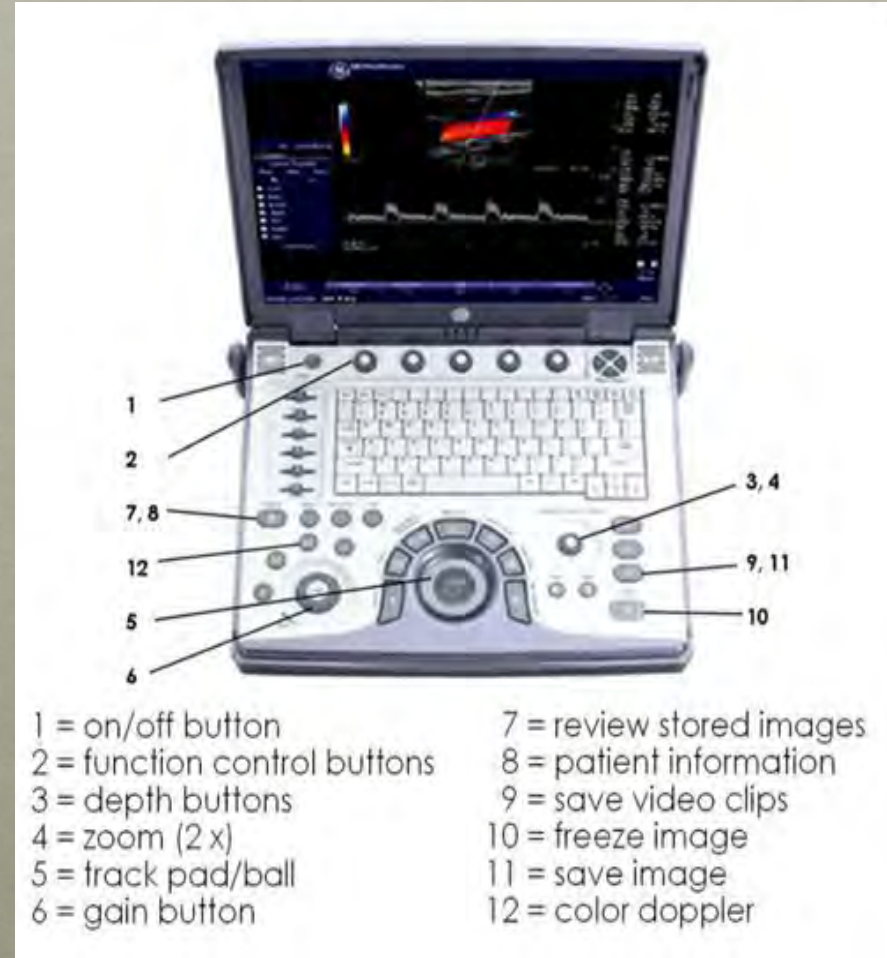


Components: 1) A pulser, 2) A transducer, 3) Receiver, 4) Display (B-mode, M-mode, A-mode), 5) Memory

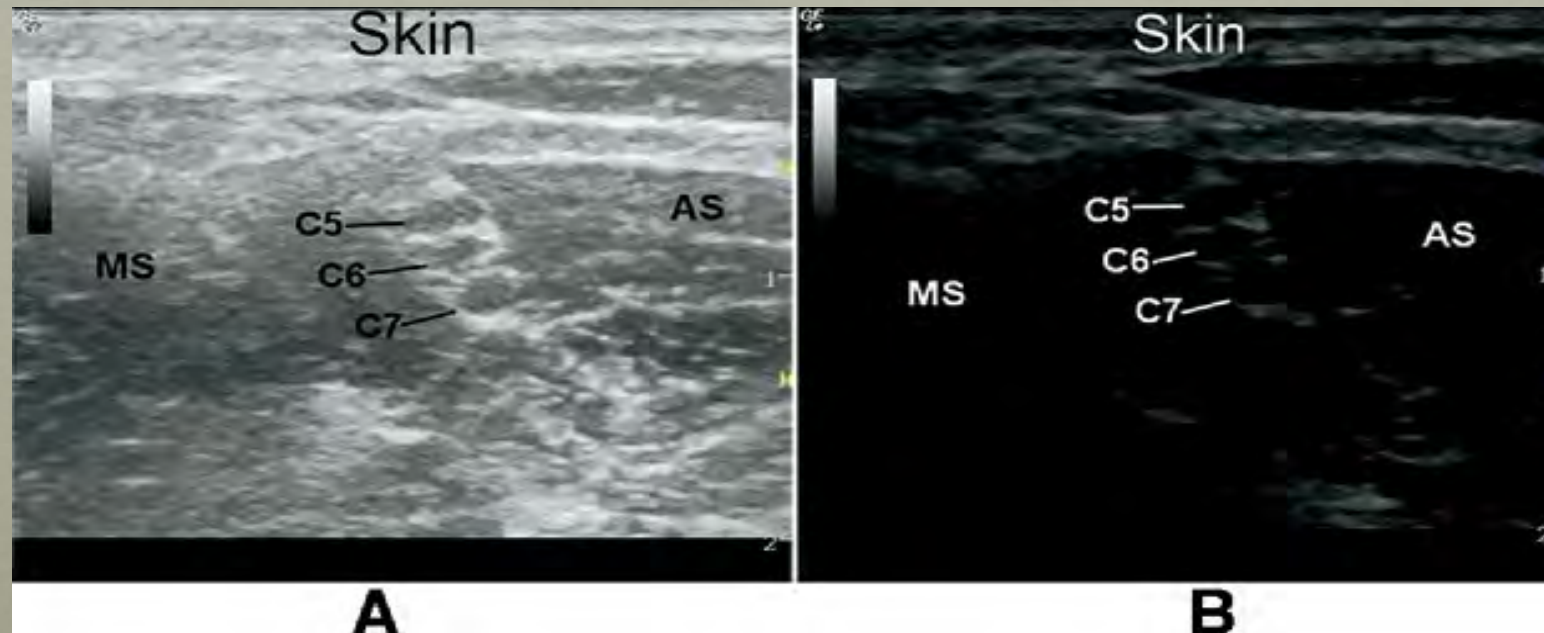
Features: 1) Compound Imaging, 2) Color Flow Doppler, 3) Contrast adjustment.

# KNOBOLOGY

- Most important
  - Gain
  - Frequency
  - Depth
  - Focal Length Button
  - Time Gain Toggle



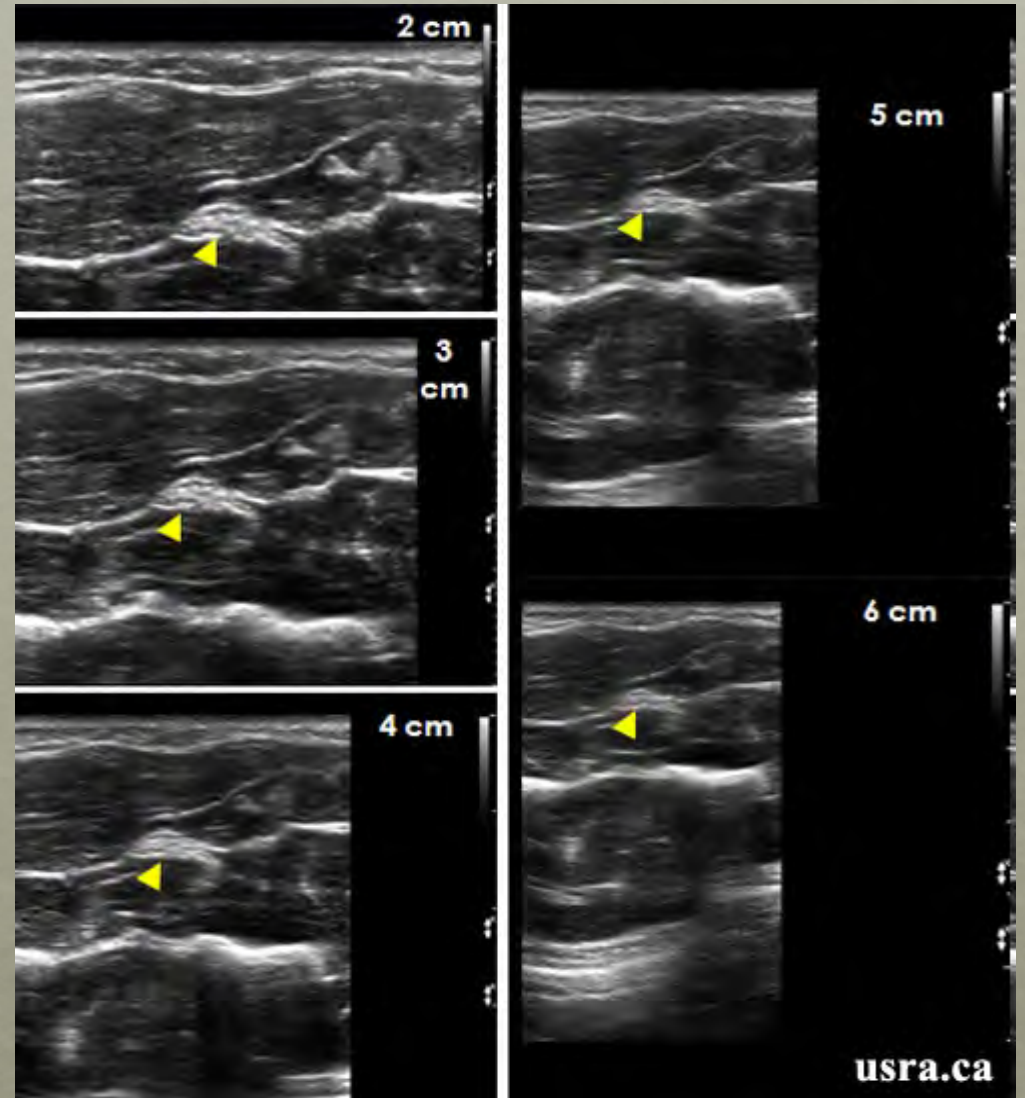
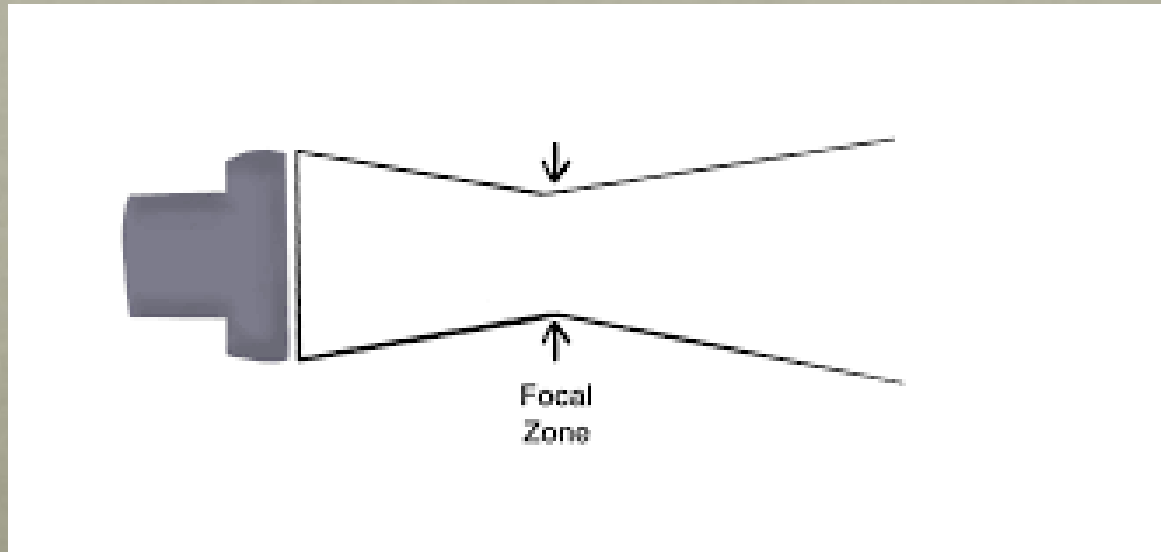
# GAIN



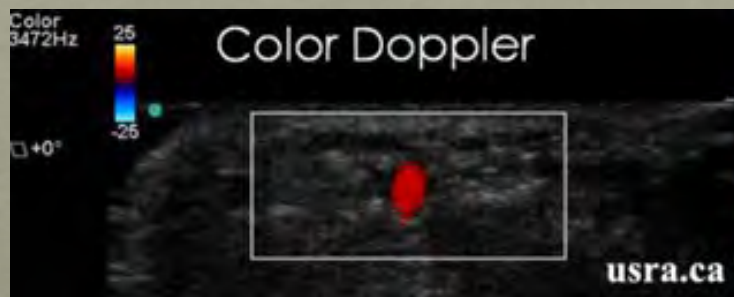
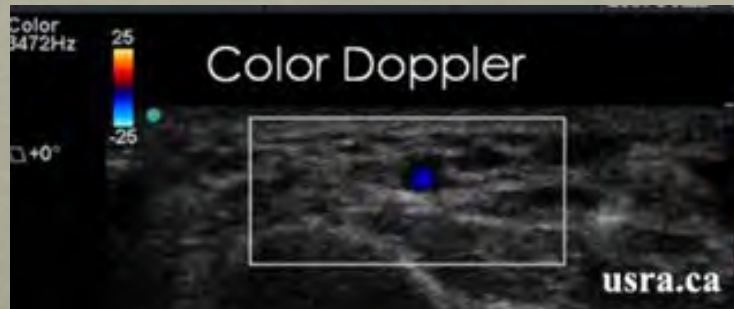
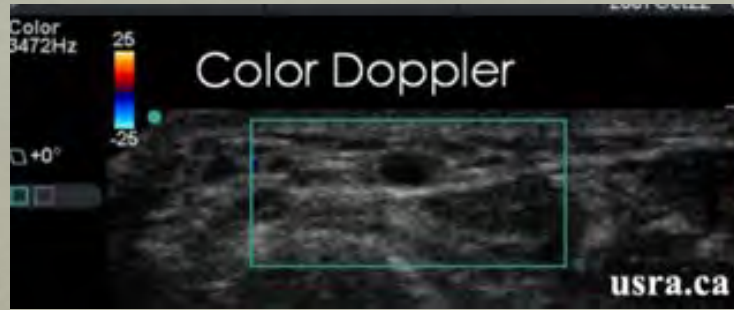
Too much

Too Little

# DEPTH



# COLOR DOPPLER



# PATIENT POSITIONING AND ERGONOMICS

- Comfortable for the patient and the operator
- Sit, stand, but ensure you are comfortable
  - Not leaning, arms 90 degrees at elbows
- I like to align my needle, US probe and US machine along the same line.
  - Many have needle and US probe perpendicular to US machine – the important thing is to have your hands in front of you and able to see the screen without turning your body.





# TIPS FOR SUCCESS

- Practice Practice Practice
  - Scan yourself, your patient, your loved one
  - Study anatomy
  - Needle control (Blue Phantom, meat)
- Do sonographic scan before block
  - Look deep for orientation and then decrease depth
- Hold needle with index finger and thumb, dominant hand
- Secure probe anchored to patient
- Consider adding stimulation to identify nerve structures
  - Hydrodissection
- Beware of common pitfalls

# TIPS FOR SUCCESS

- Start with easier, superficial blocks, and then progress.
- Basic level blocks: Femoral, interscalene, and popliteal.
- Advanced: Higher sciatic (infragluteal, parasacral, ), anterior sciatic, TAP, infraclavicular, supraclavicular, PENG.

# COMMON MISTAKES

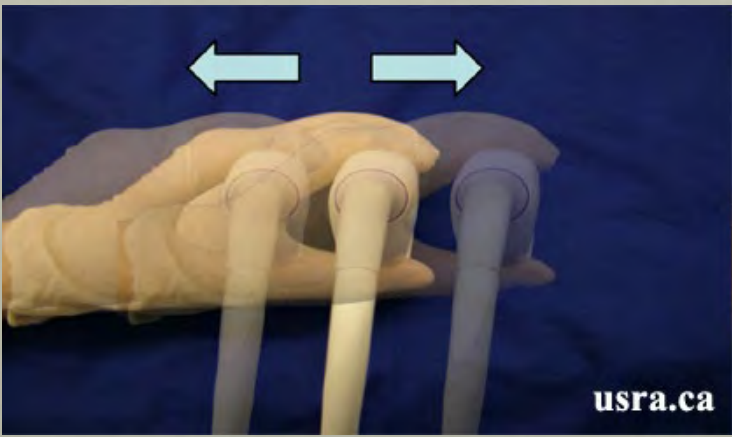
- Remember
  - Specular image
  - If you don't, tip may not be where you think



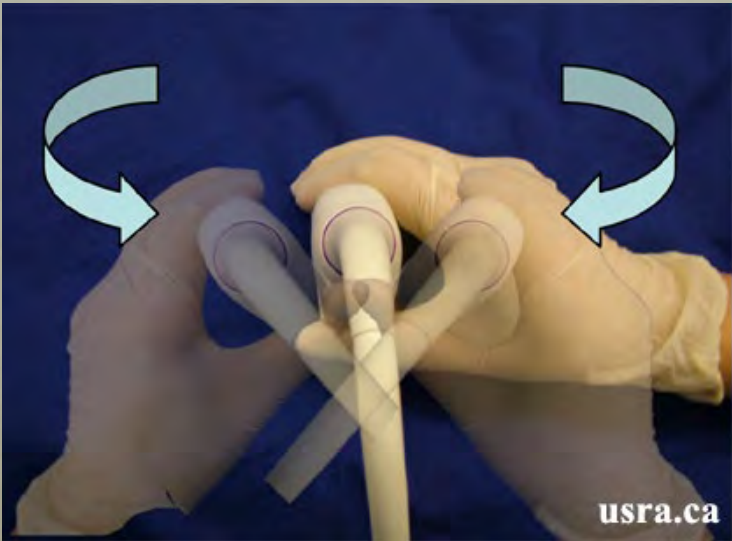
# COMMON MISTAKES

- If you don't see the entire shaft, you may not have needle tip in view.
- Think “ART”
  - Alignment
  - Rotation
  - Tilt

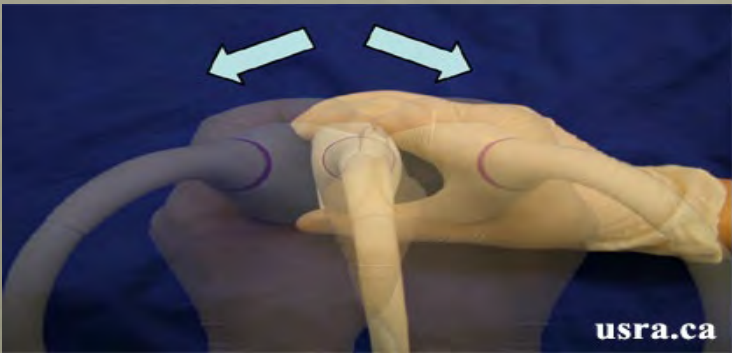




- A = Alignment



- R = Rotation



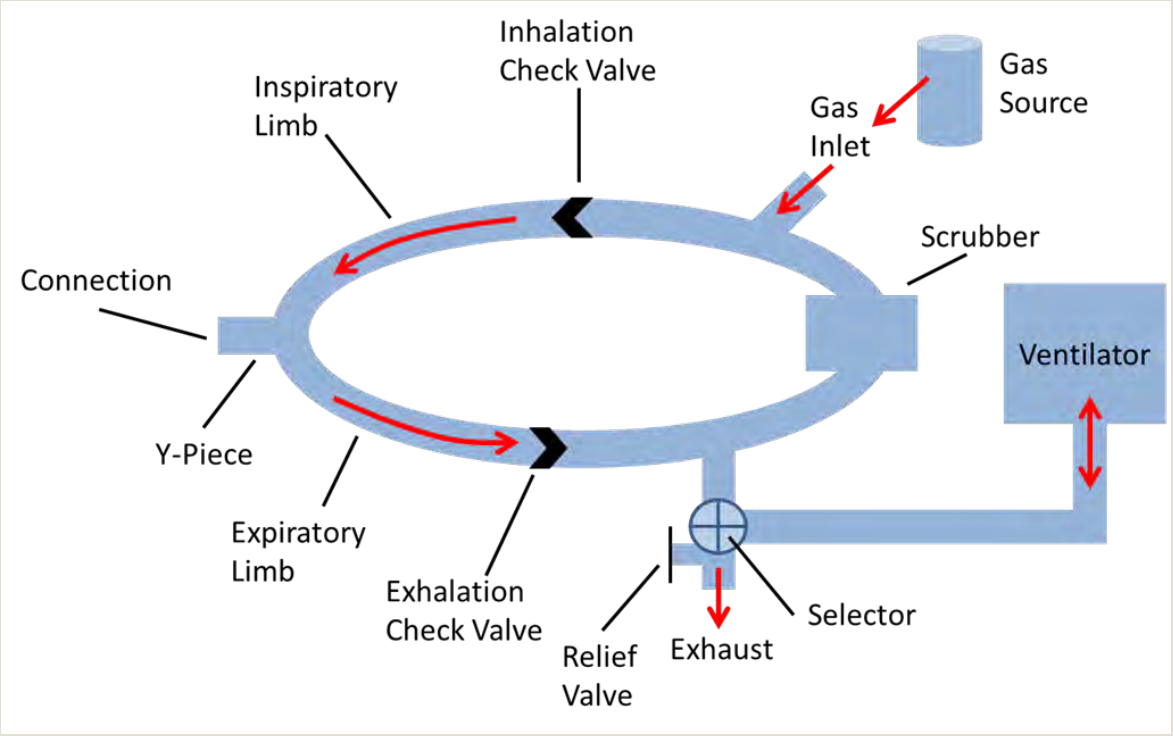
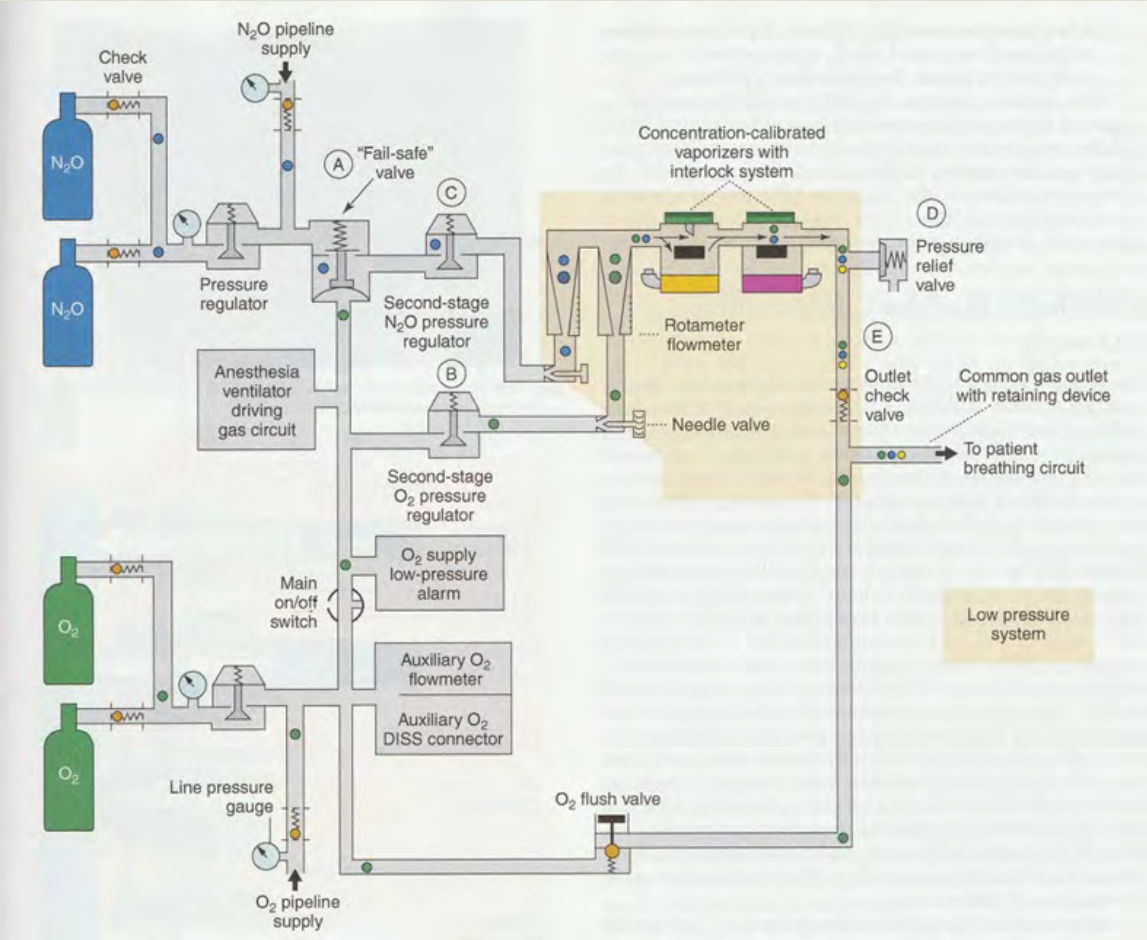
- T = Tilt



# ANESTHESIA TECHNOLOGY

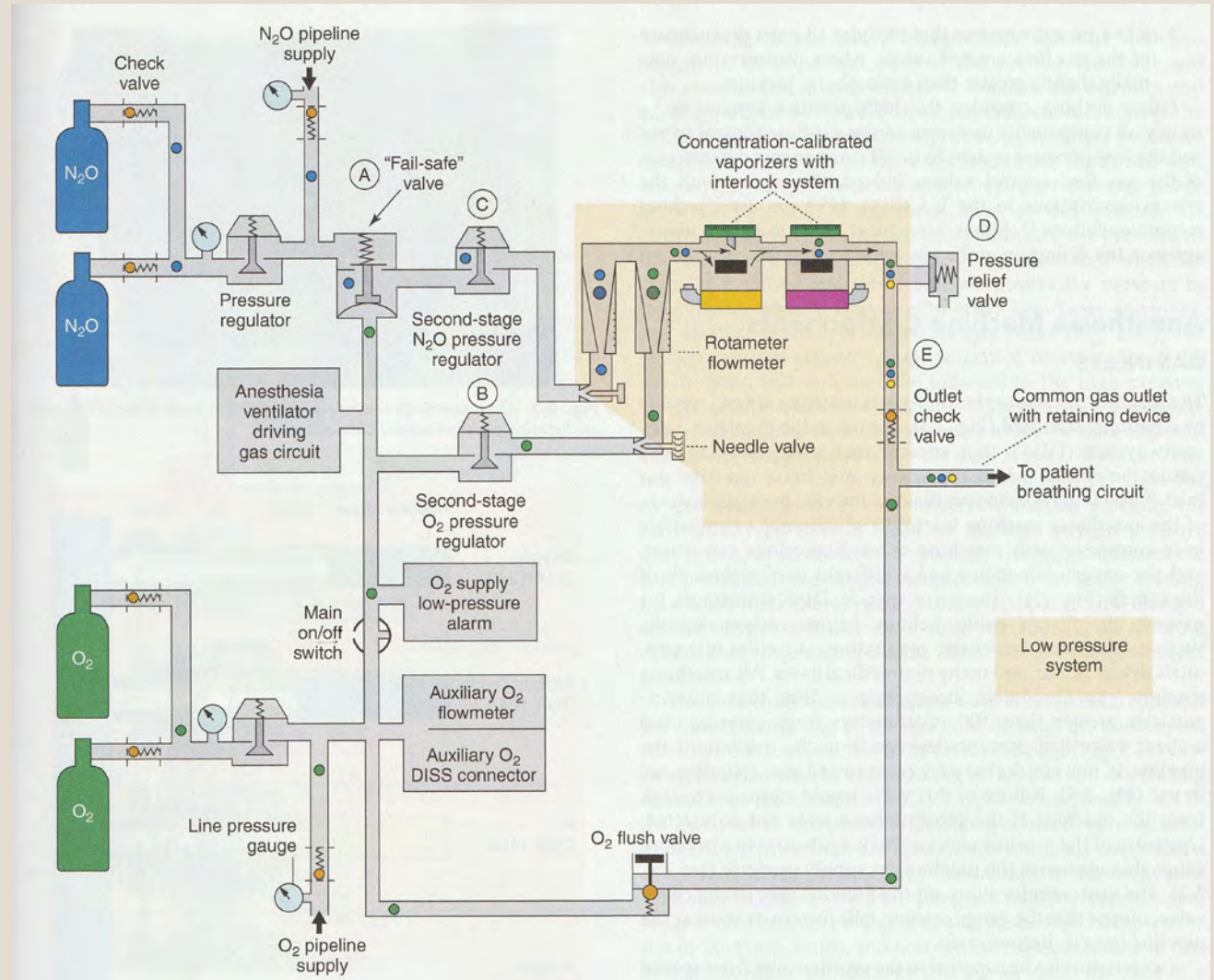
Derek Owens DrAP, CRNA

# Anesthesia Machine



# Gas flow

- Wall pipeline
  - 50-55 psi
- Cylinder pressure
  - 40-45 psi

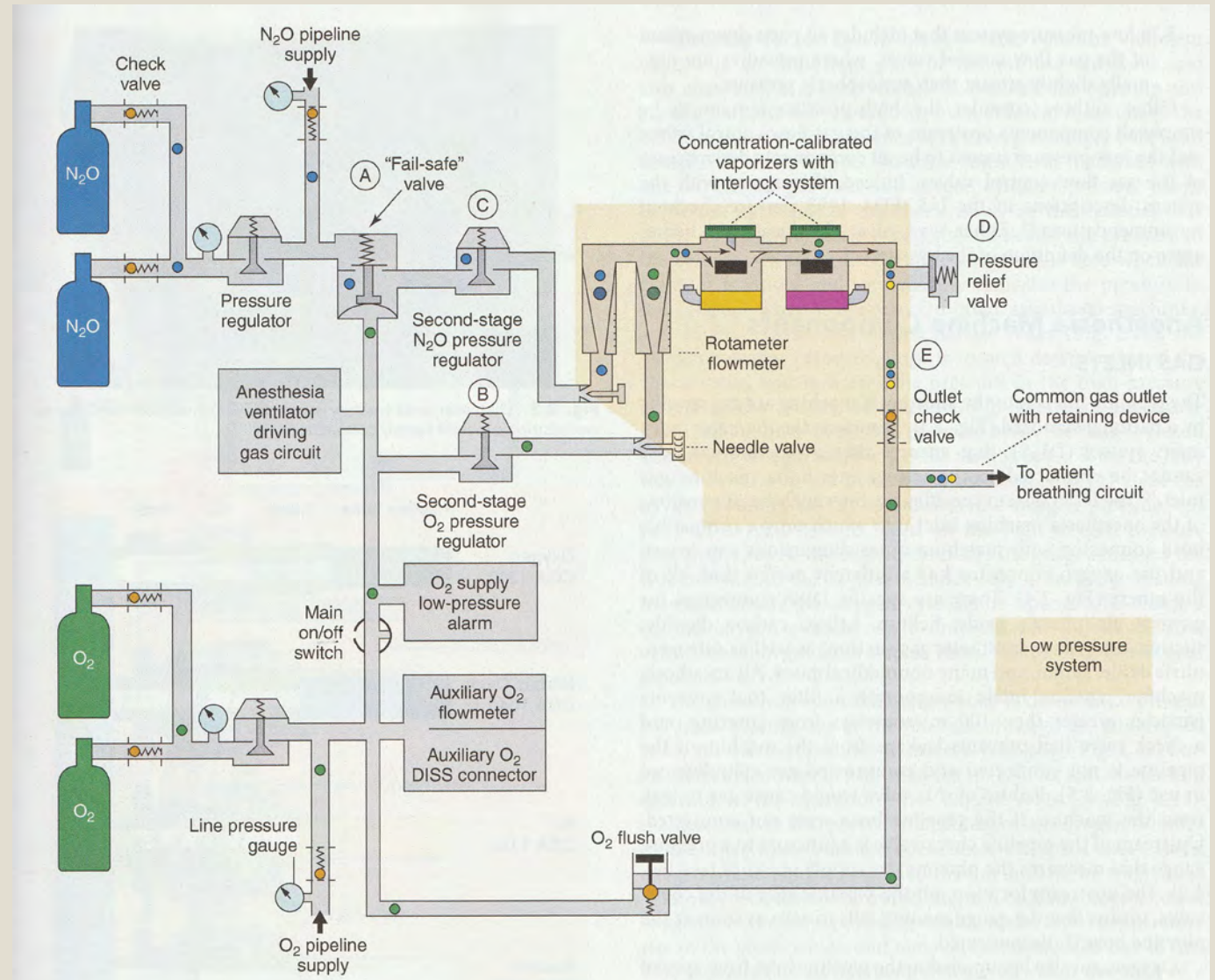




# Gas Flow

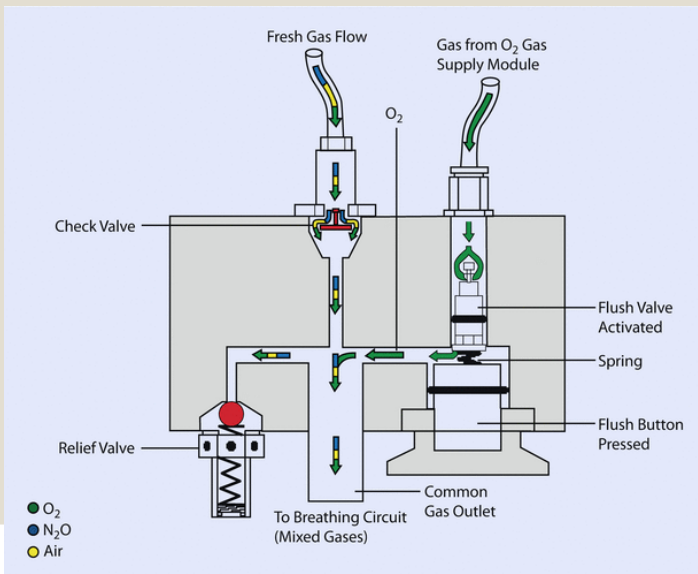
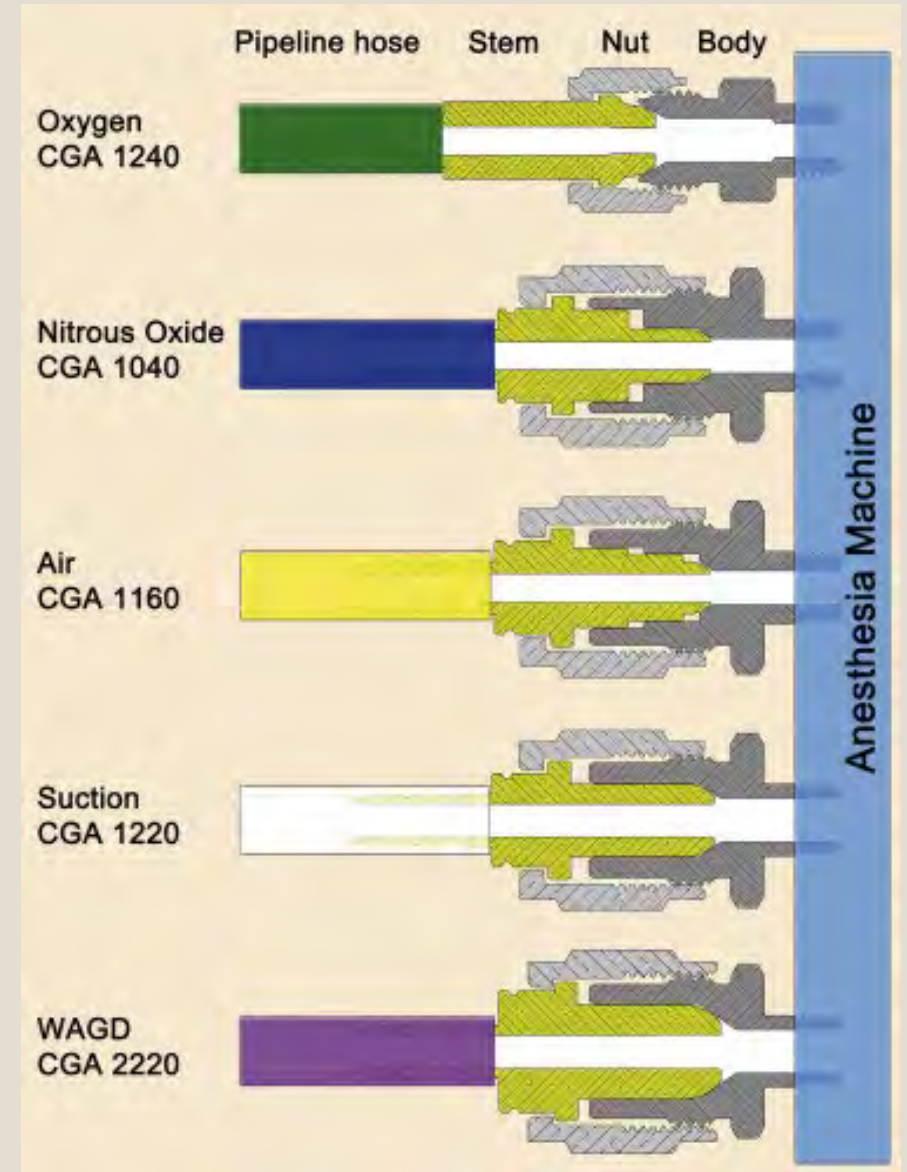
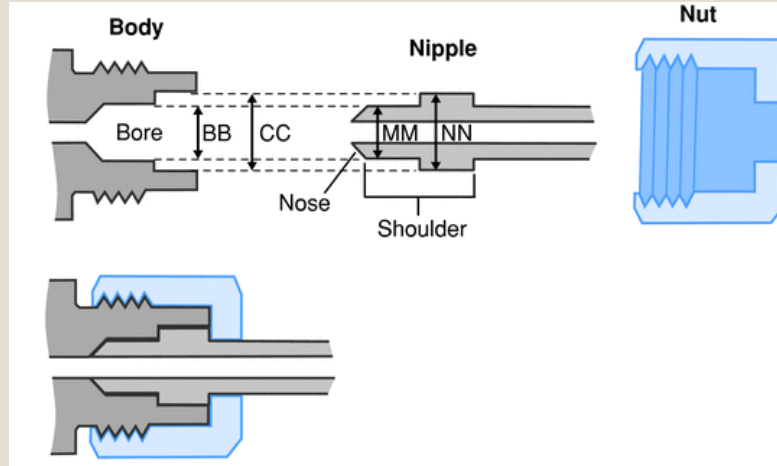
◦  $\text{Flow} = \frac{\text{Pressure}}{\text{Resistance}}$

- High Pressure
  - 55-2200 psi
- Intermediate Pressure
  - 16-55 psi
- Low Pressure
  - Slightly greater than atmospheric psi



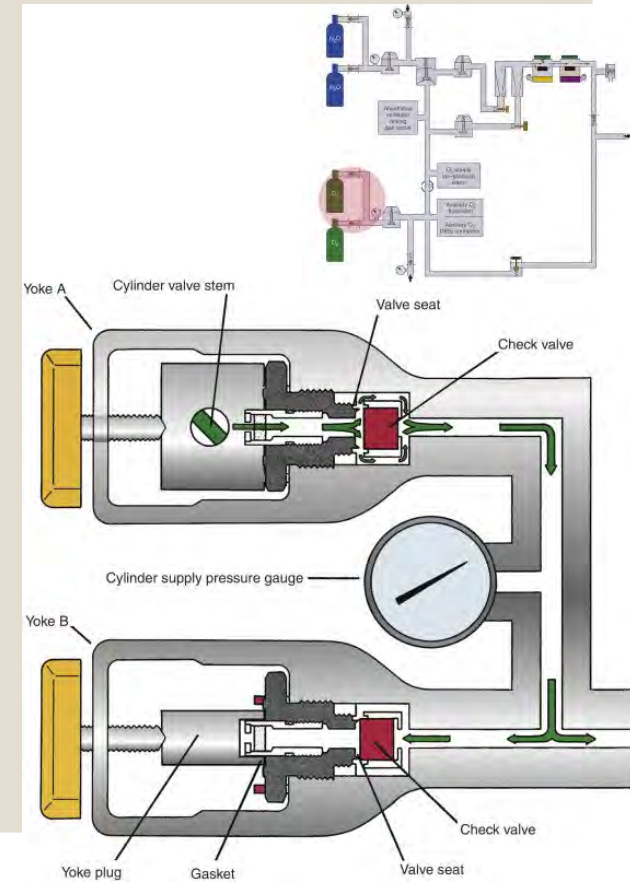
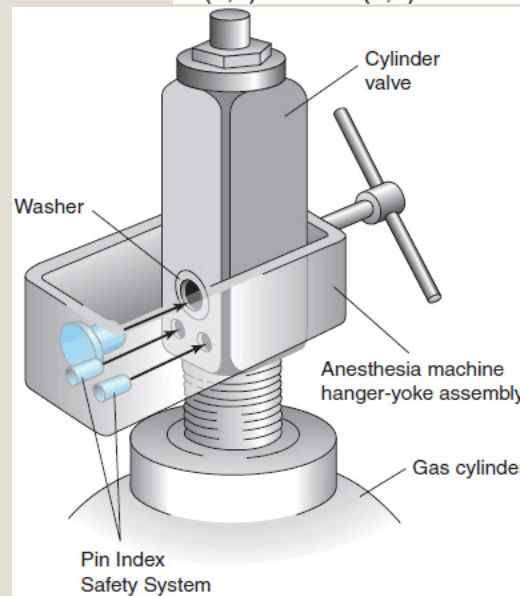
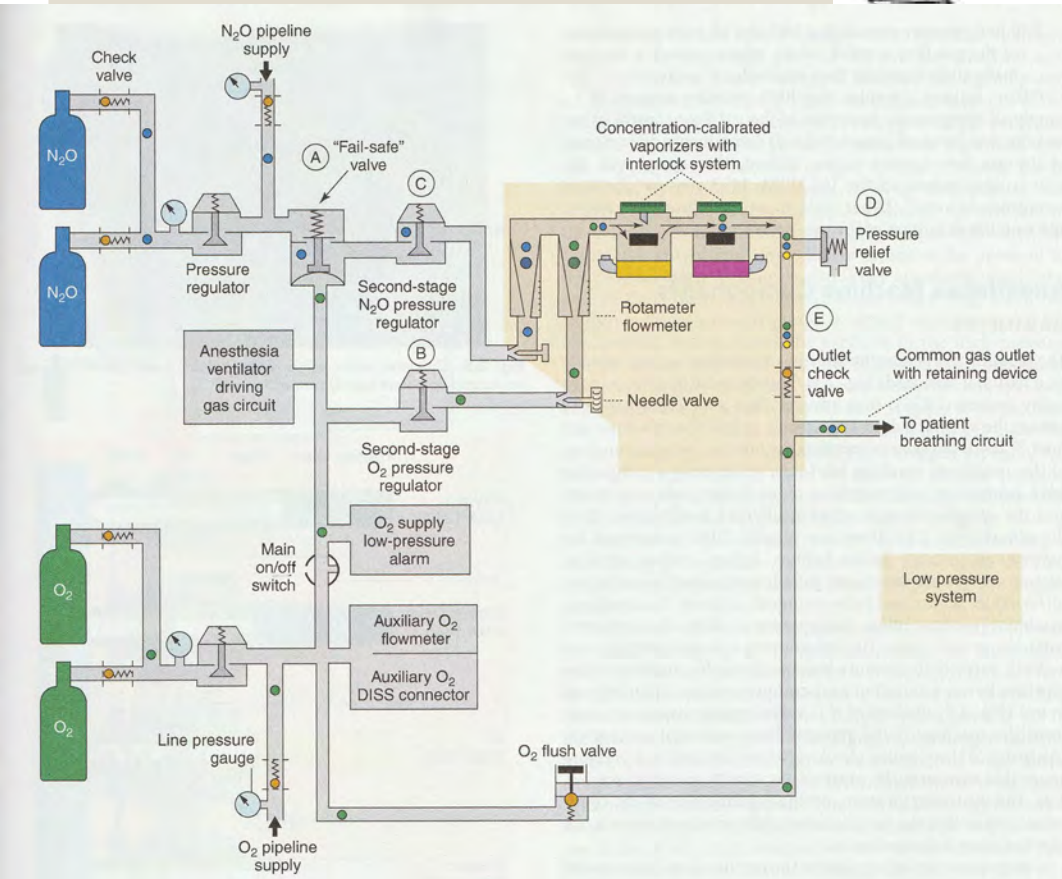
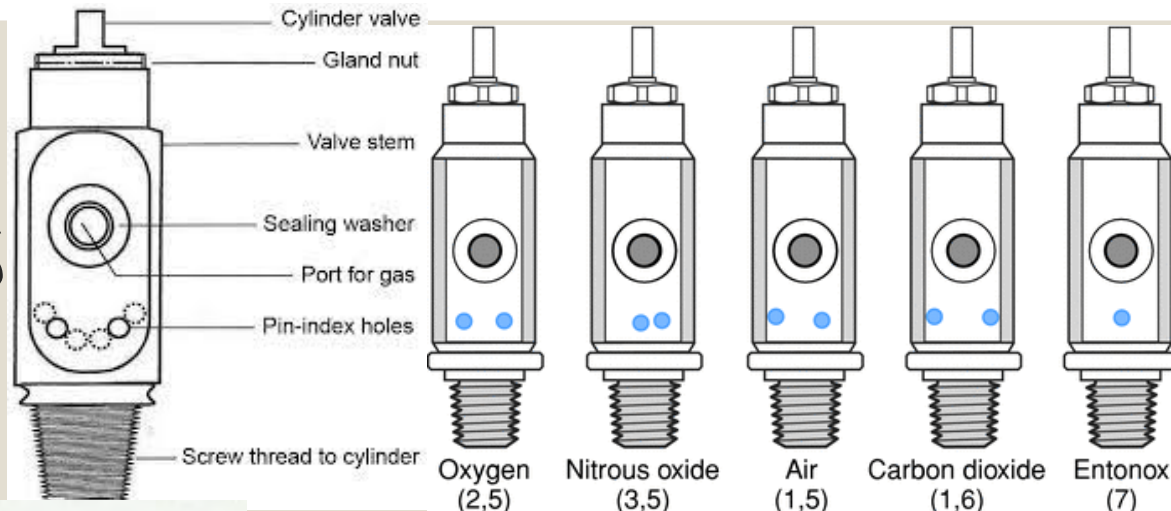
# Gas inlets

- DISS



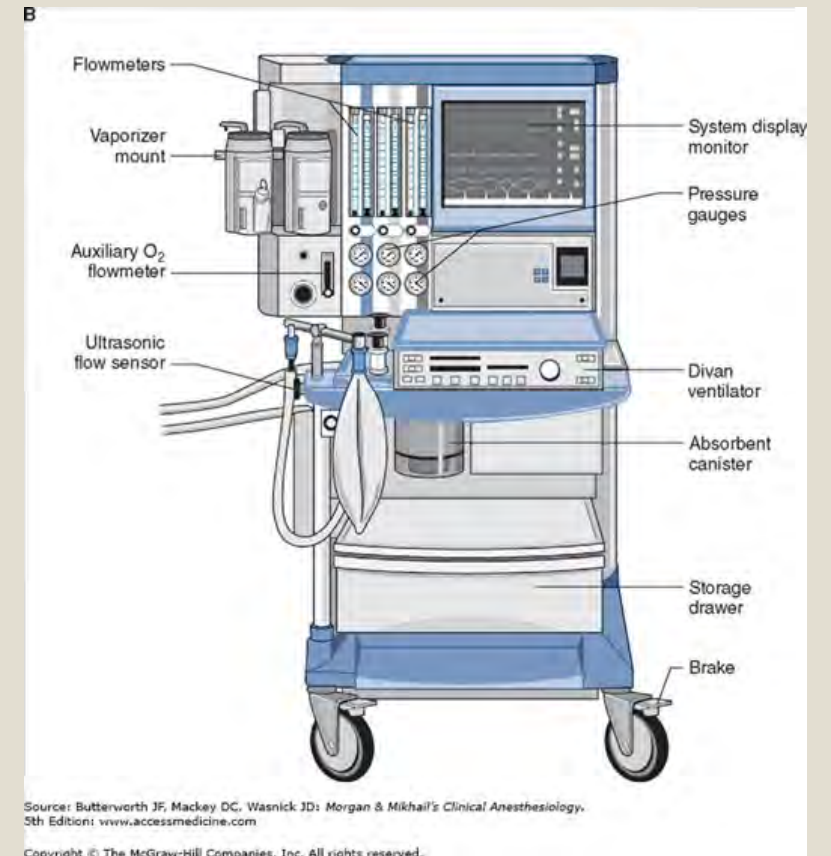
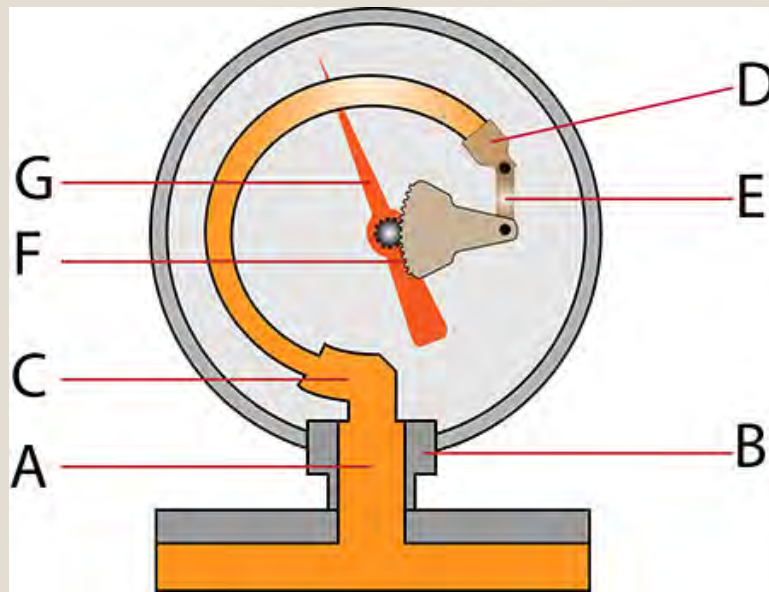
# Gas inlets

o PISS



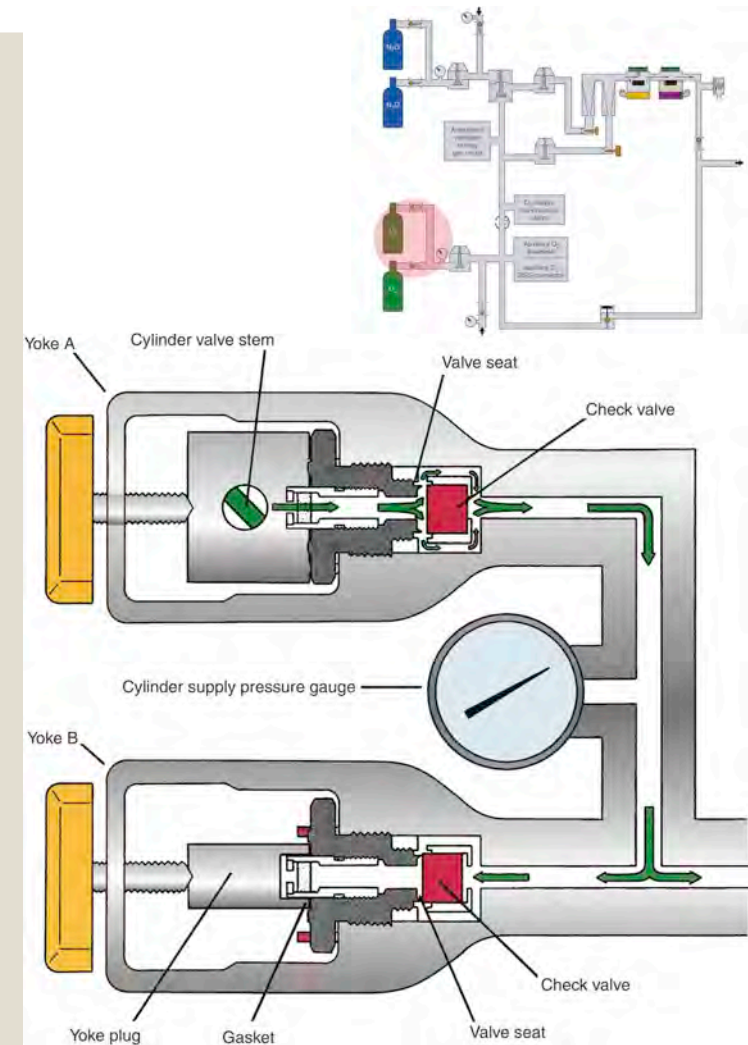
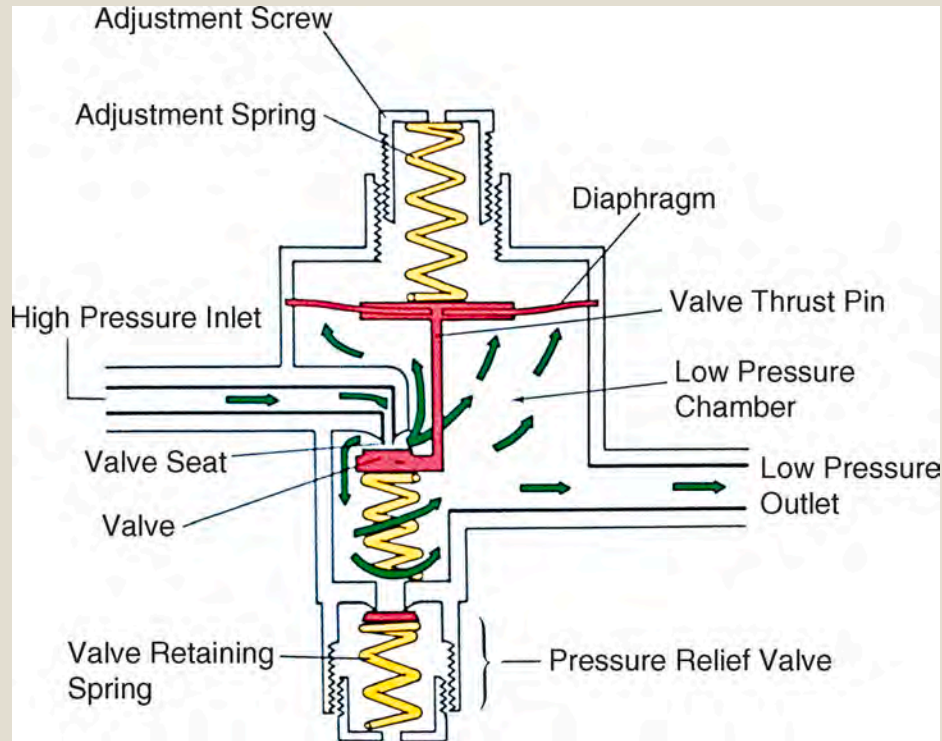
# Gauges

- Bourbon tube

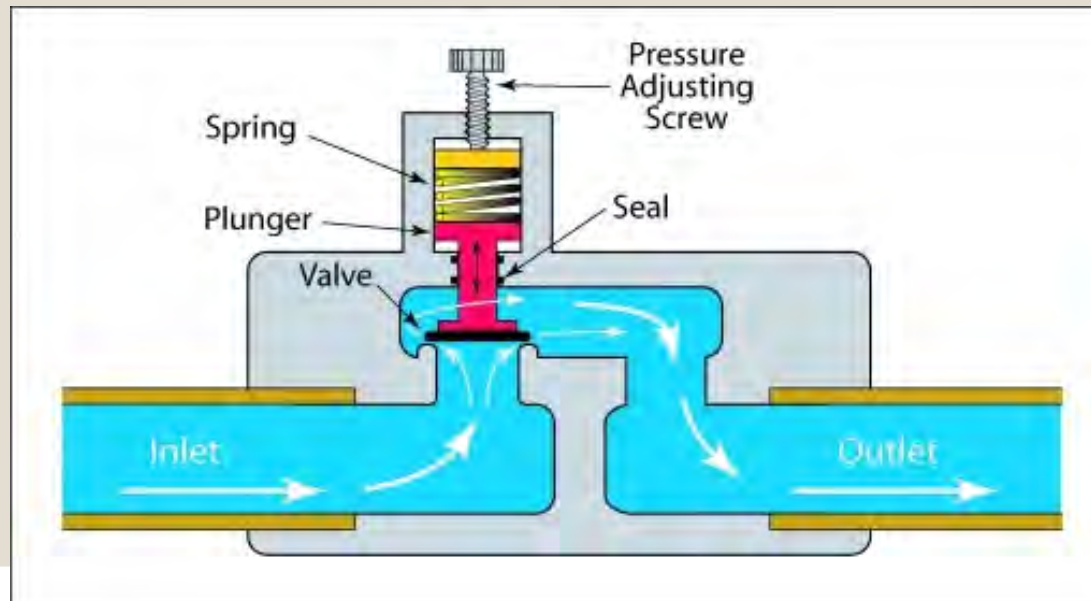
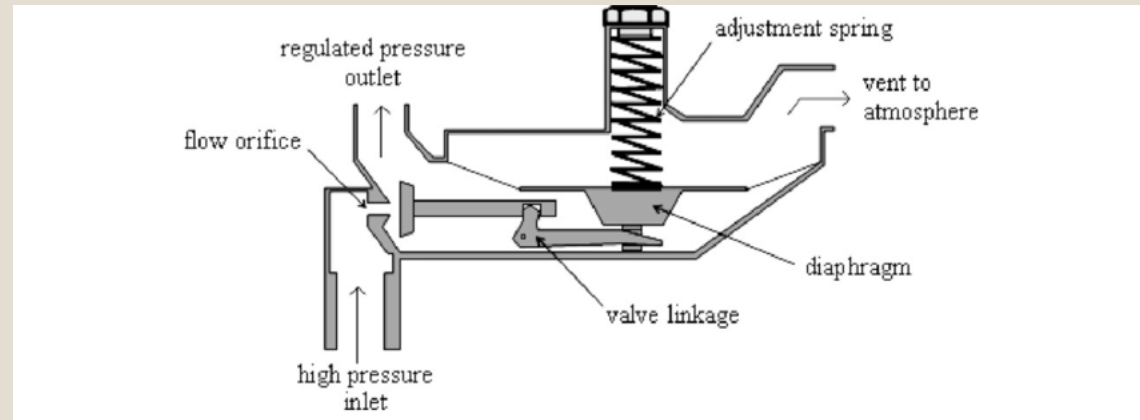


# Cylinder supply

- Hanger yoke

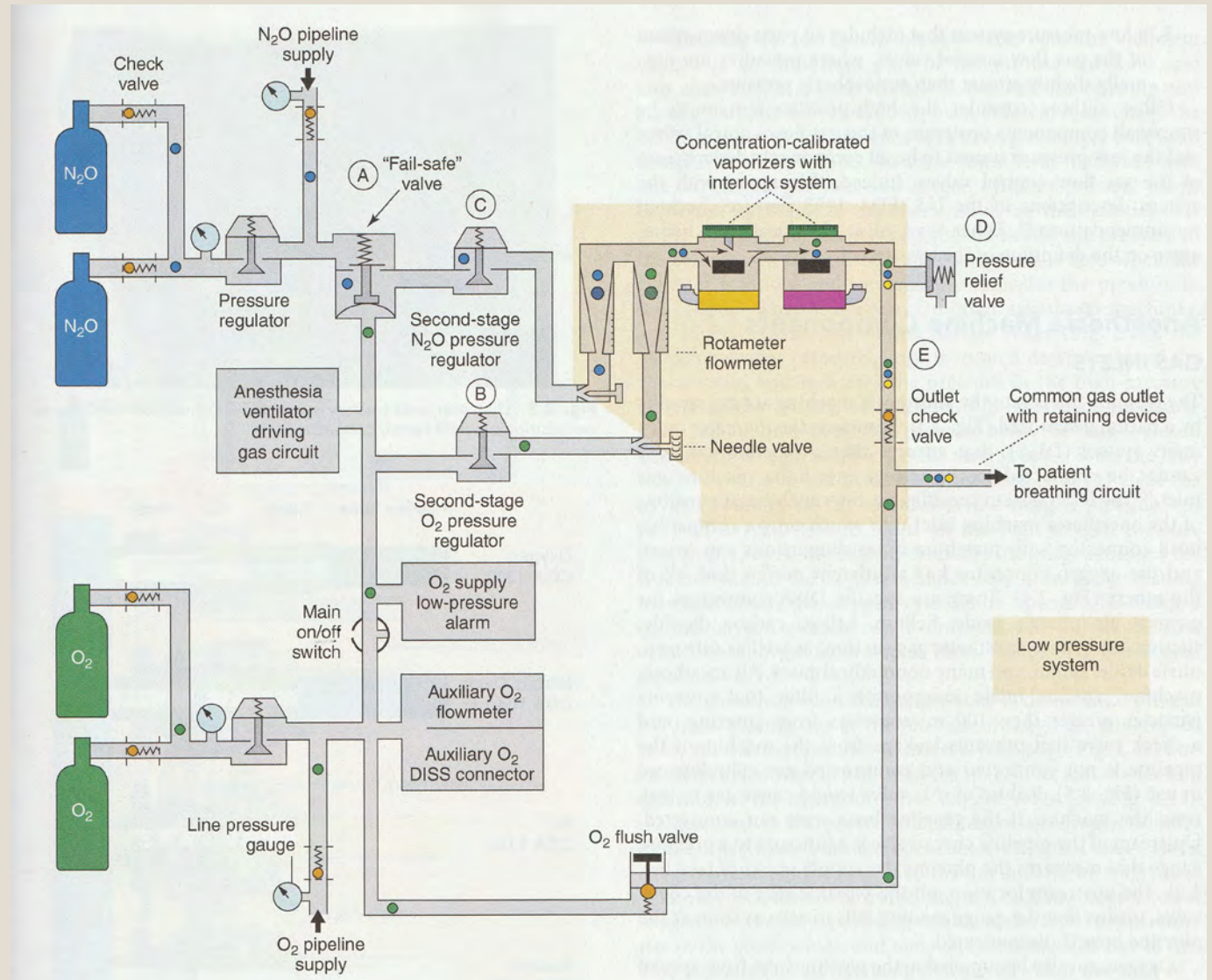


# Pressure regulators



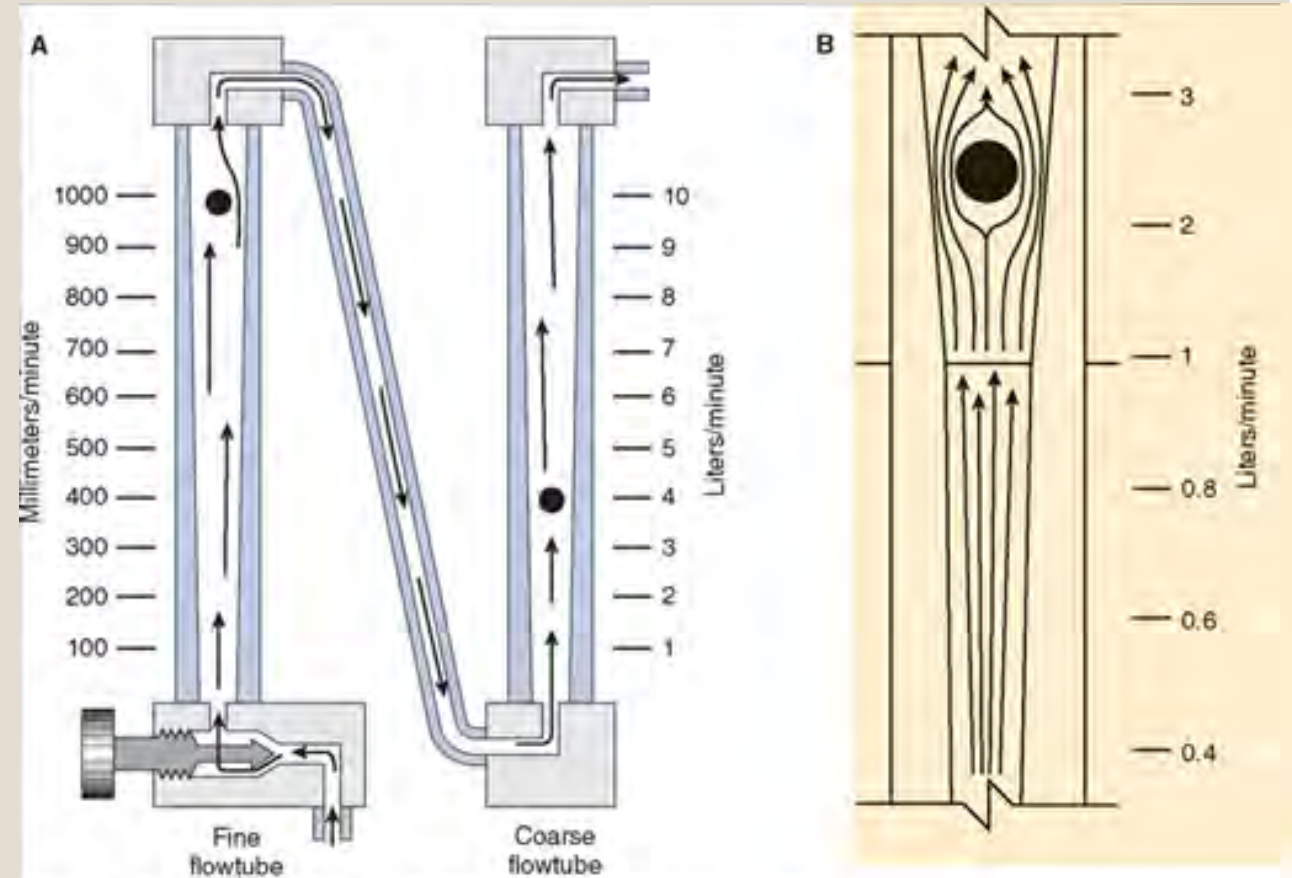
# Intermediate

- High Pressure
  - 55-2200 psi
- Intermediate Pressure
  - 16-55 psi
- Low Pressure
  - Slightly greater than atmospheric psi



# Mechanical flowmeters

- Calibrated for a single gas

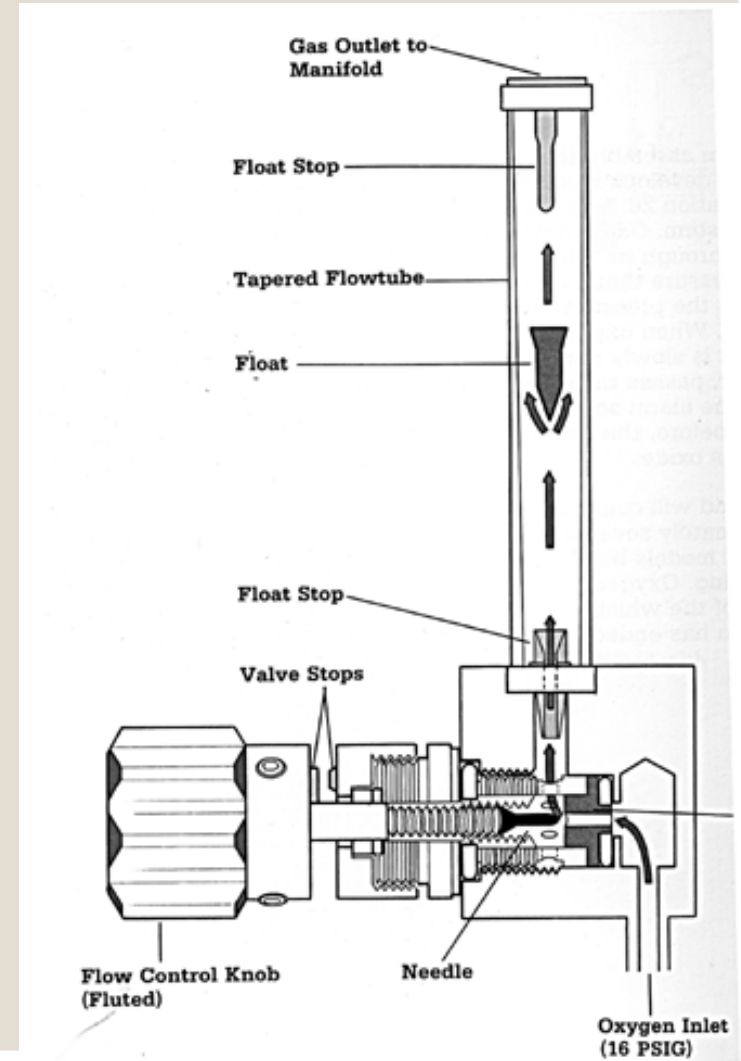
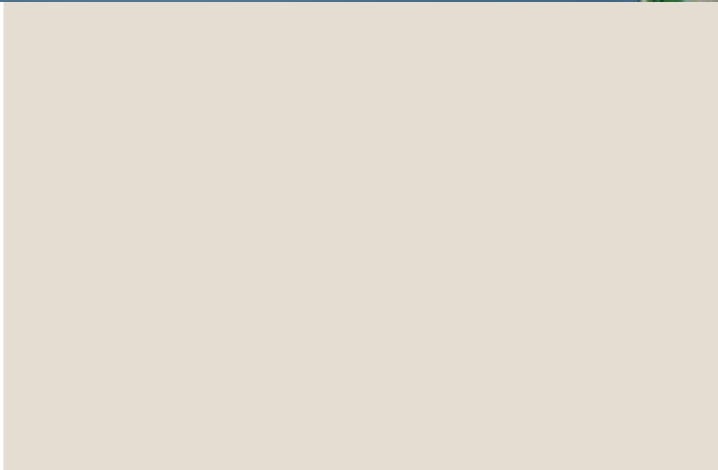


Source: Bultenworth JF, Mackey DC, Wasnick JD: *Morgan & Mikhail's Clinical Anesthesiology*, 5th Edition: [www.accessmedicine.com](http://www.accessmedicine.com)

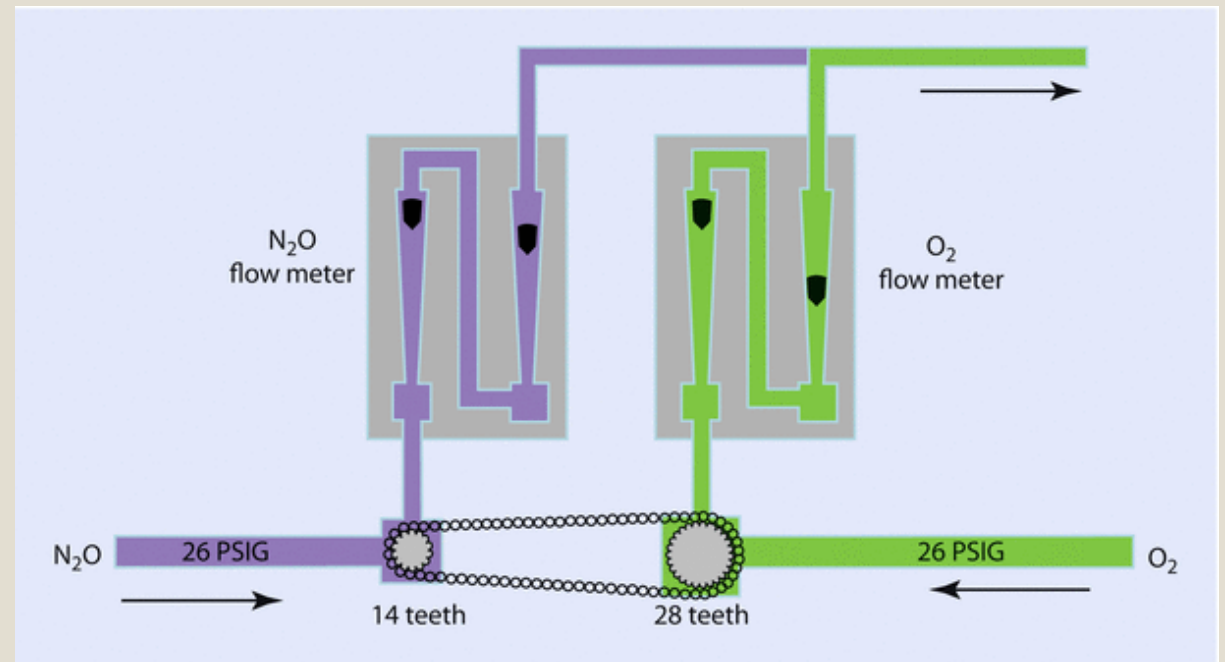
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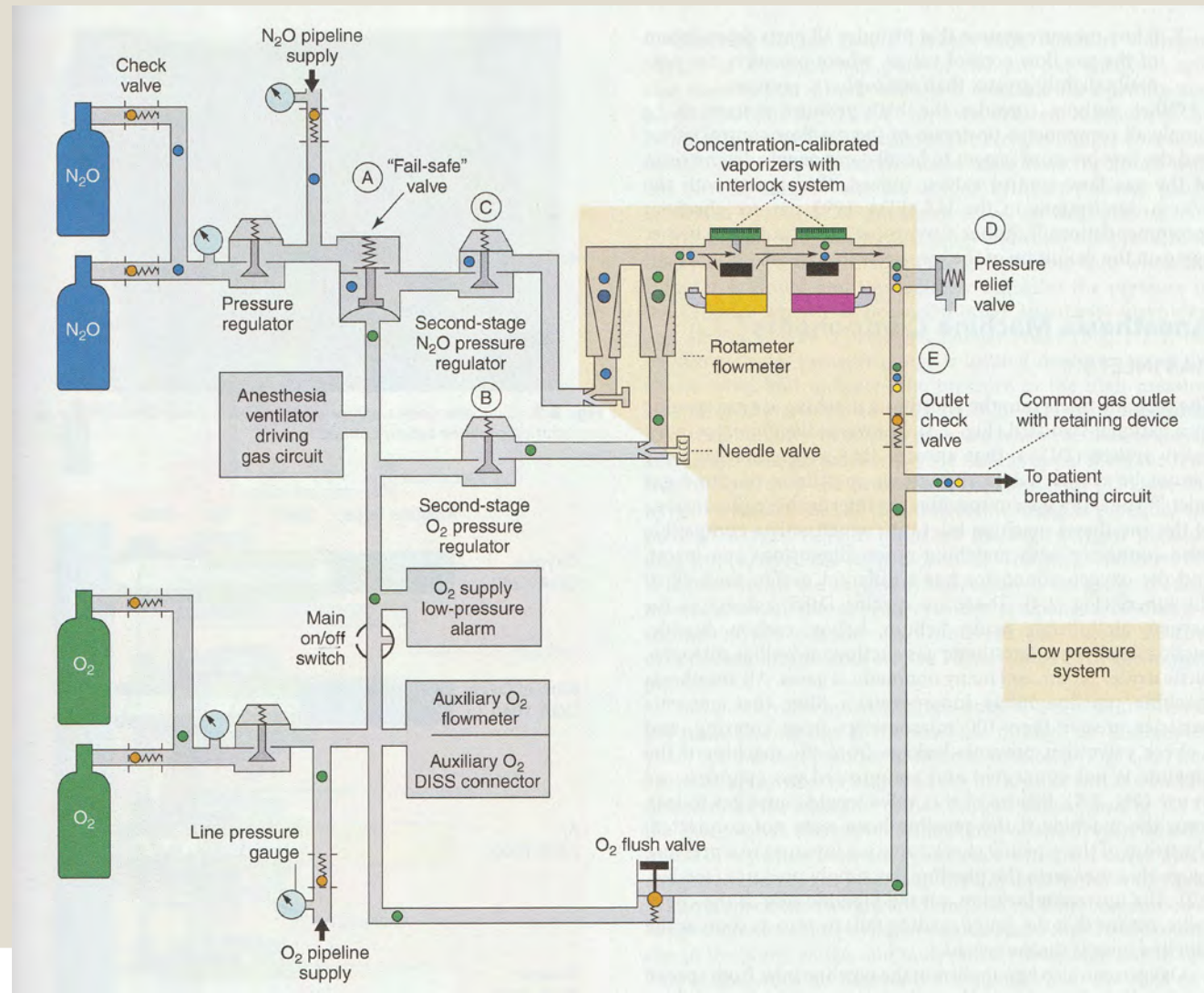
# Mechanical flow control valves



# Oxygen ratio proportioning system

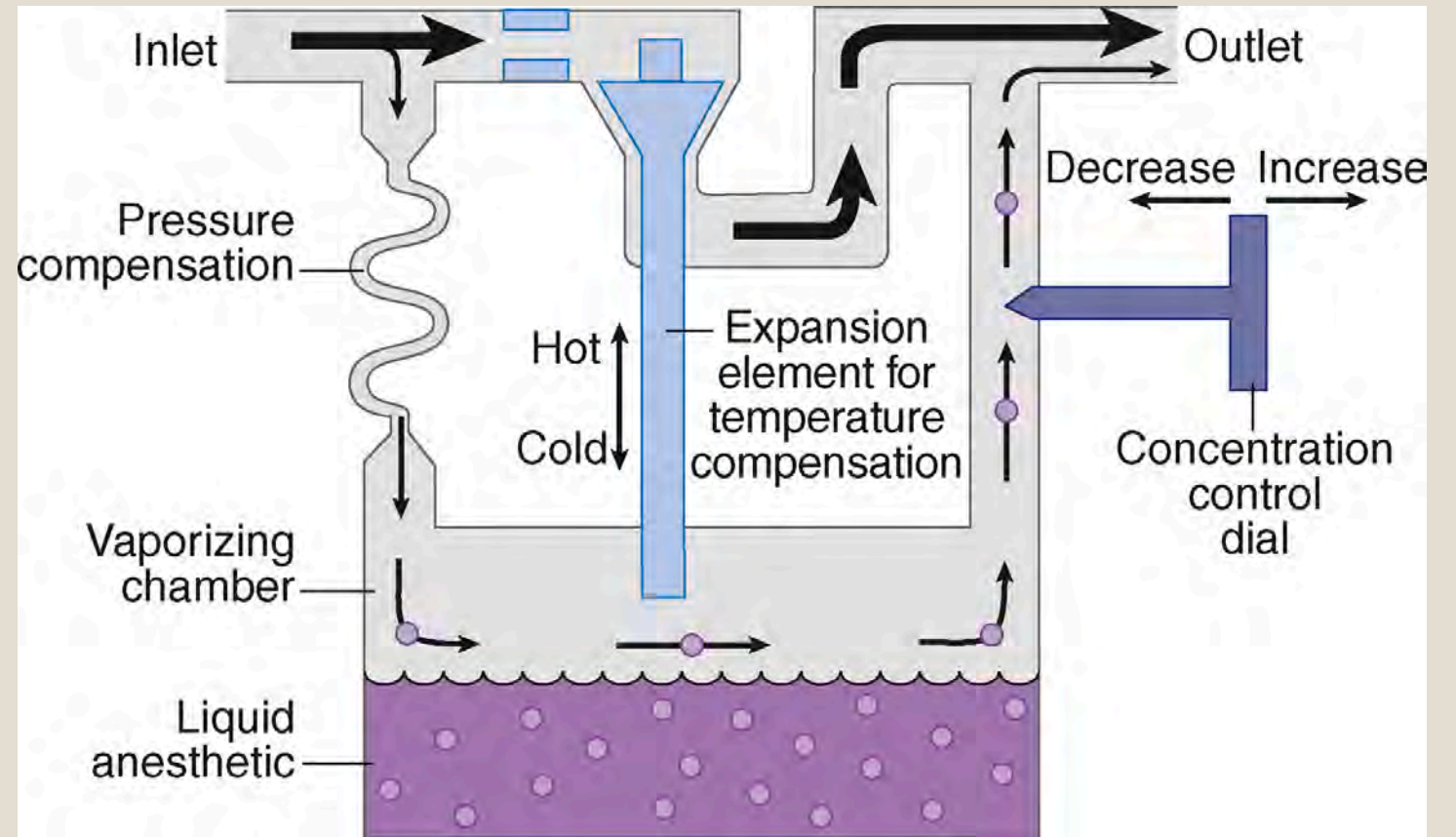


# Alarms

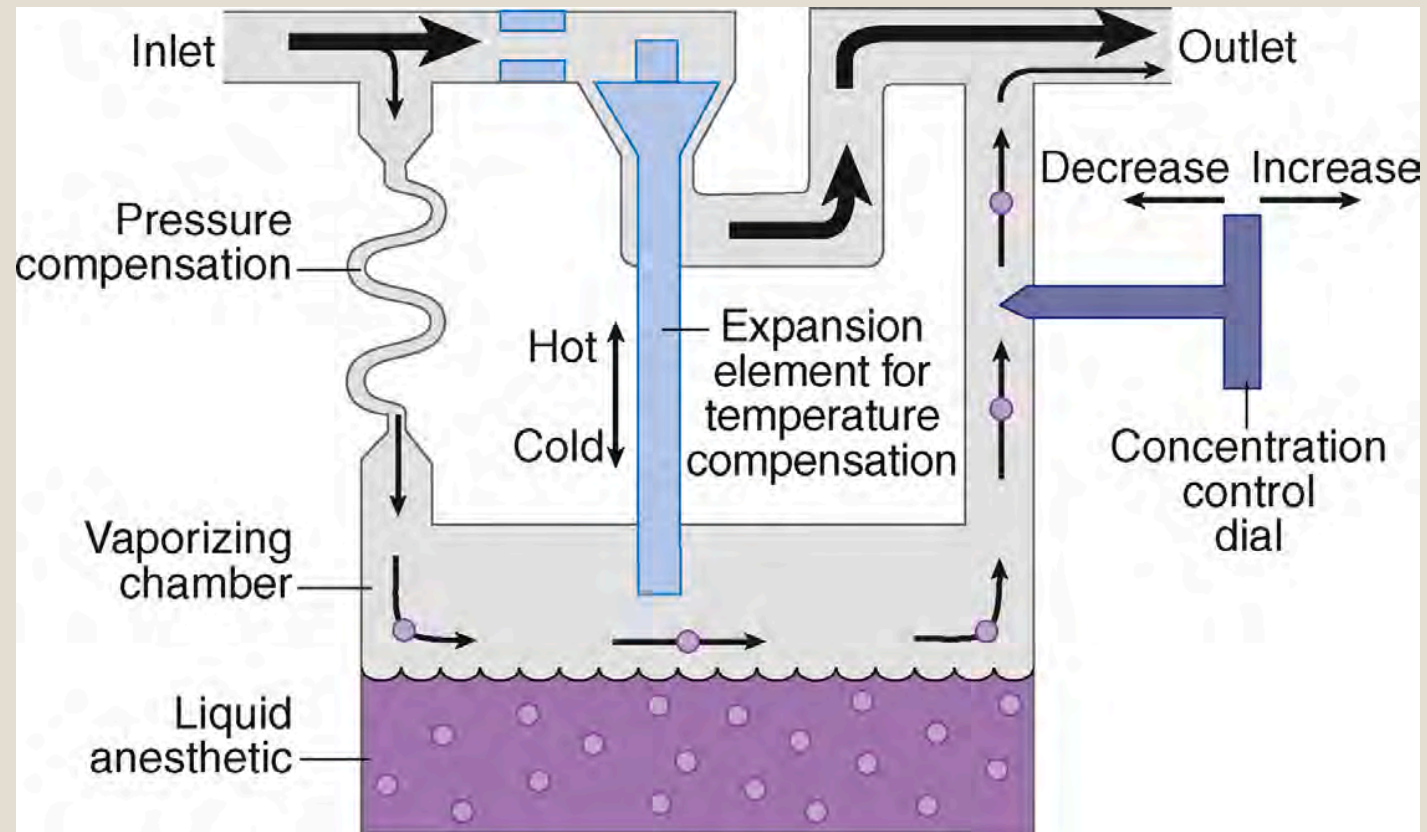


# Vaporizers

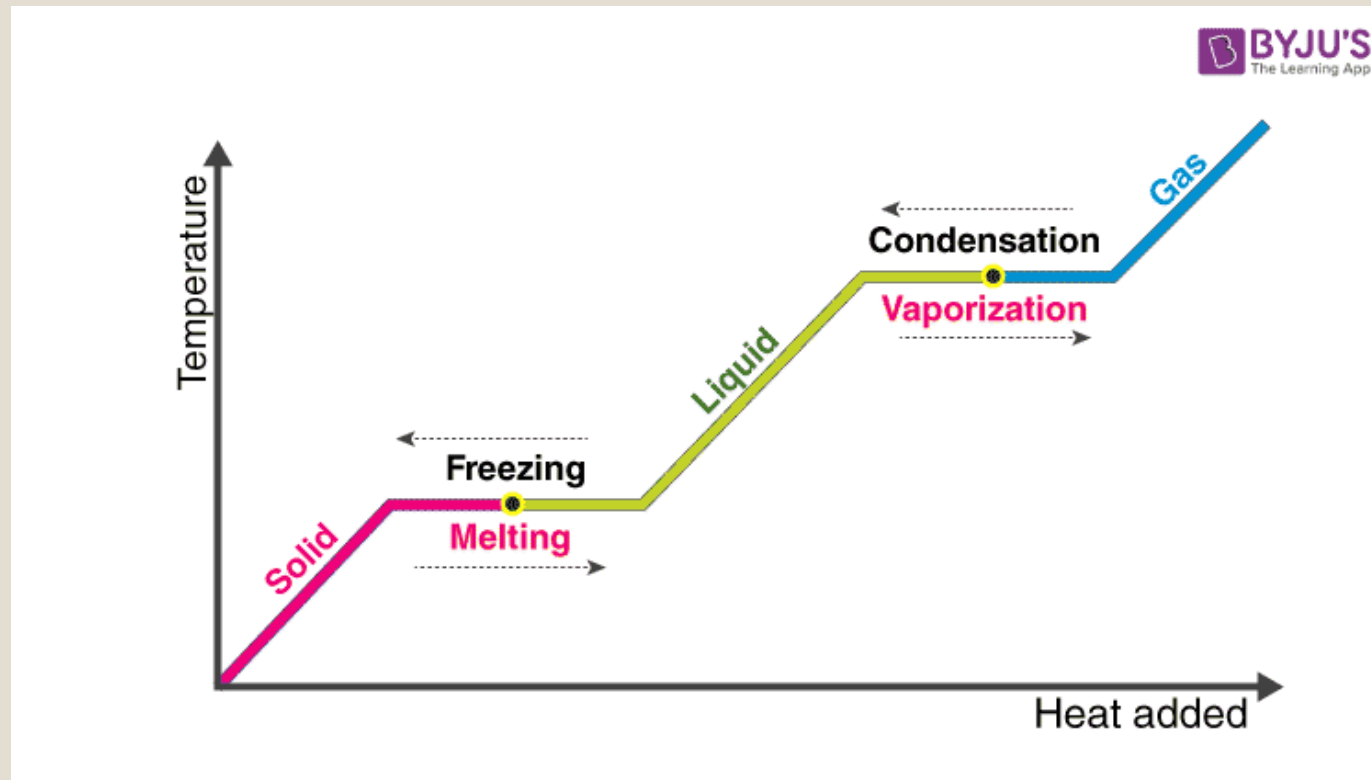
- Variable bypass



# Vaporizers

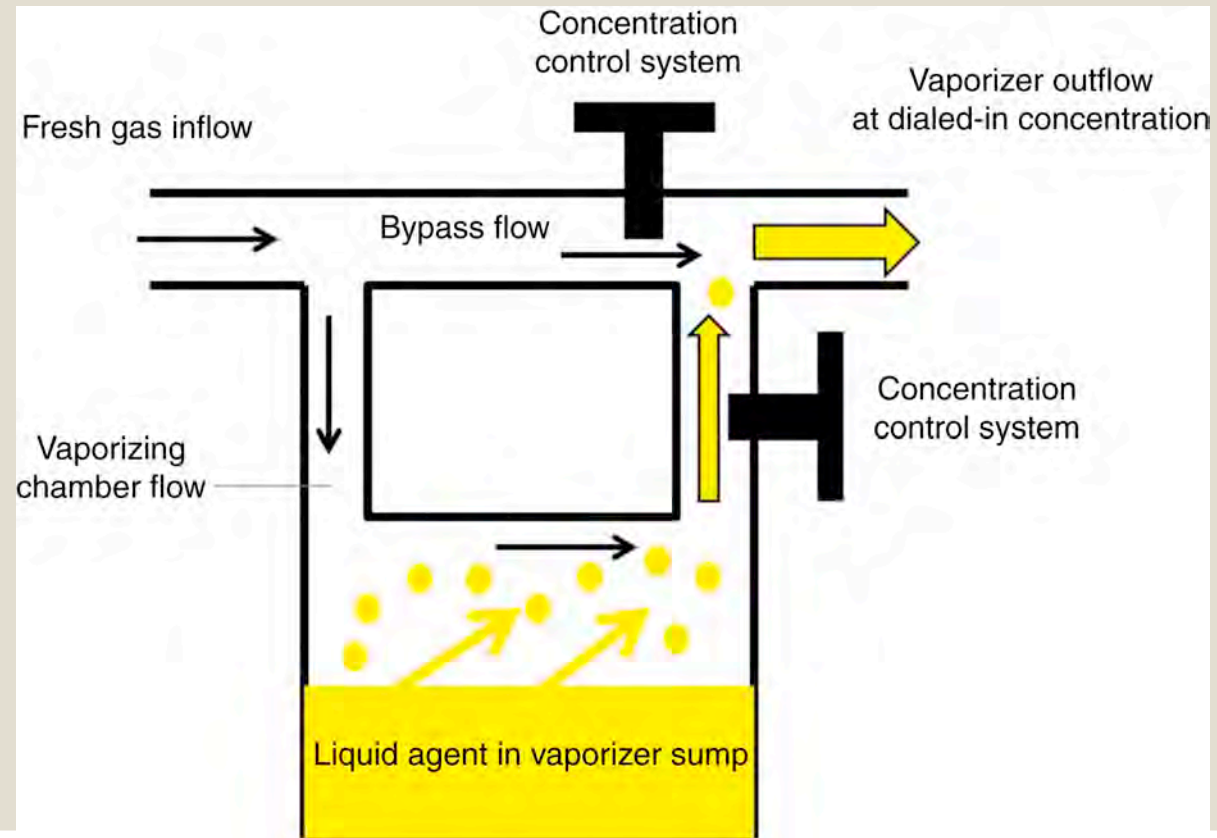


# Latent heat of vaporization

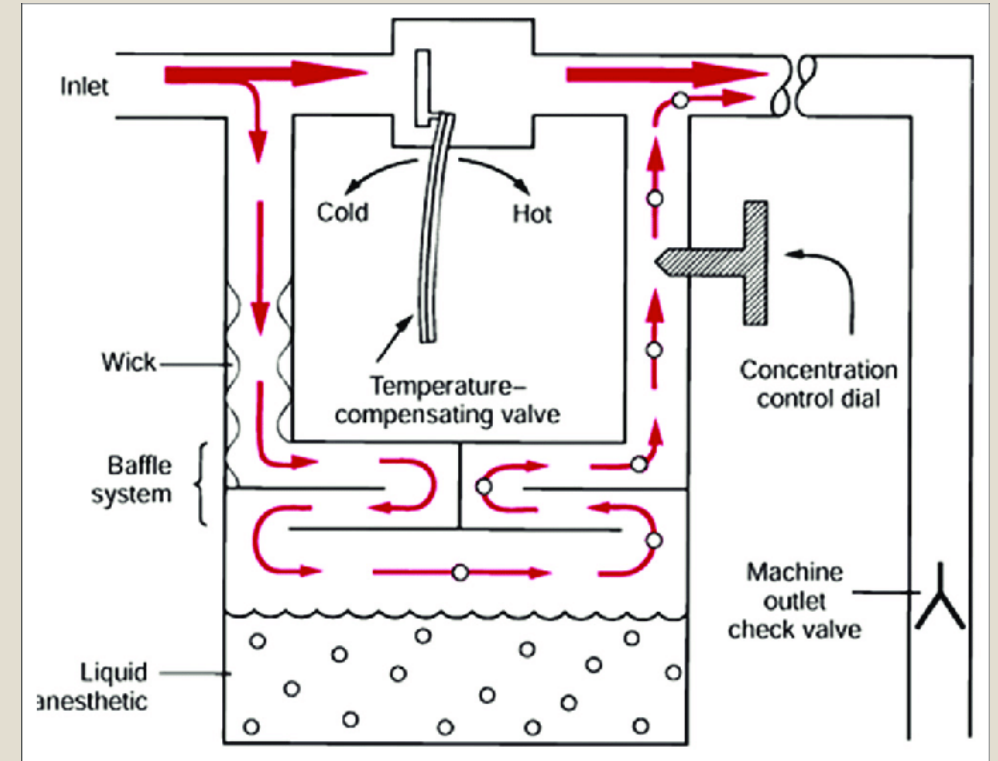


# Regulating output

- Concentration calibrated variable bypass



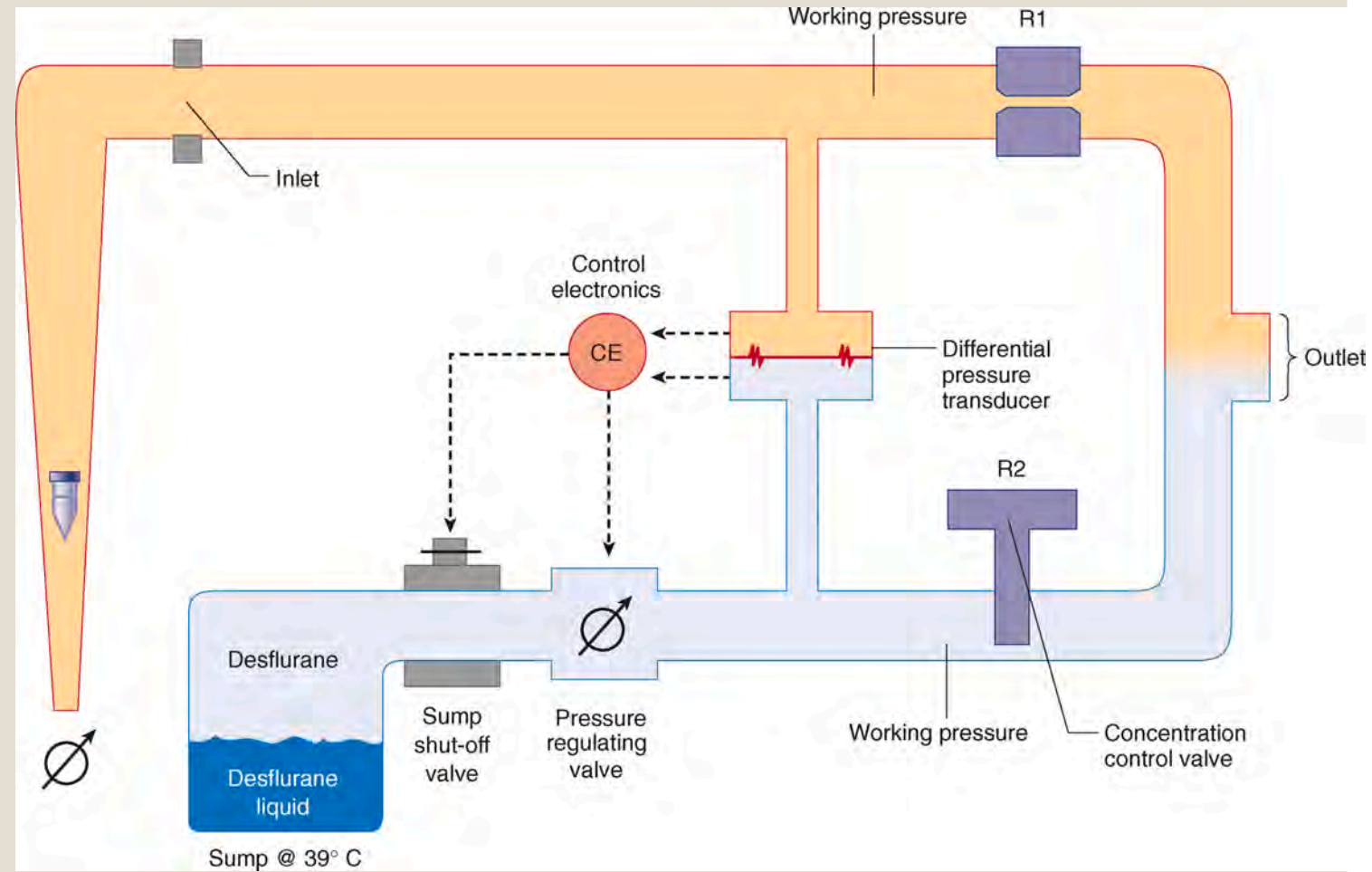
# Temperature compensation



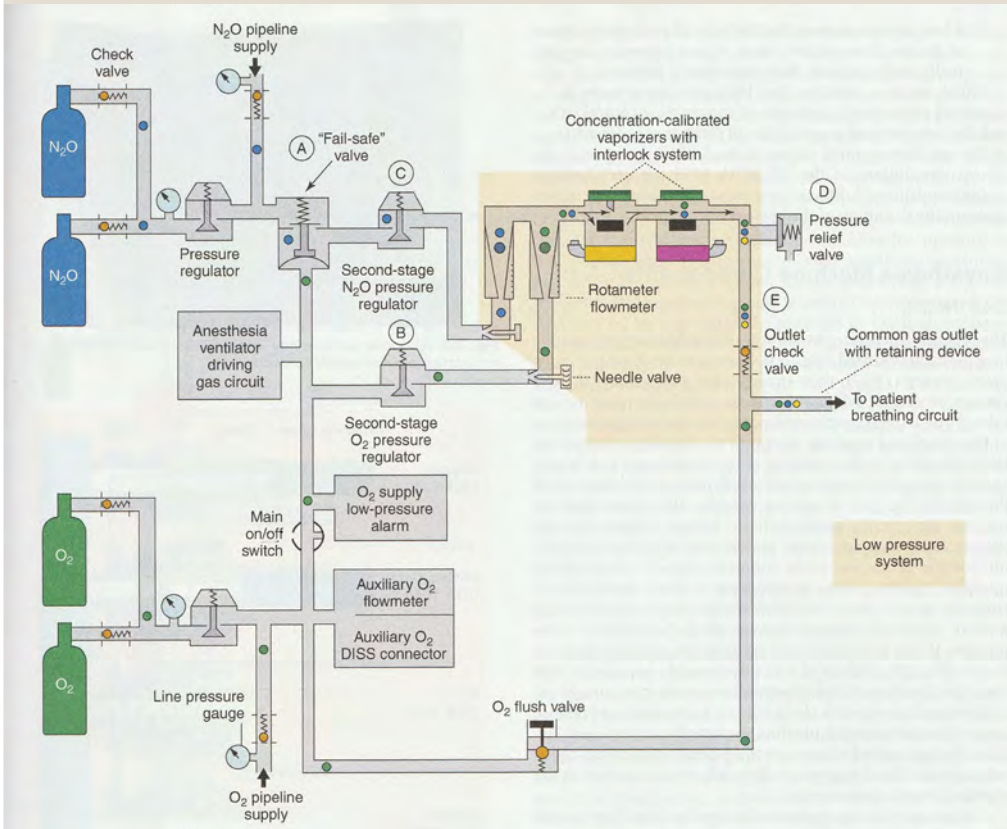


# Vaporizer classification and design

- Tec 6
  - Control points
    - Concentration dial
    - Differential pressure transducer



# Freestanding vaporizer



# Common gas outlet

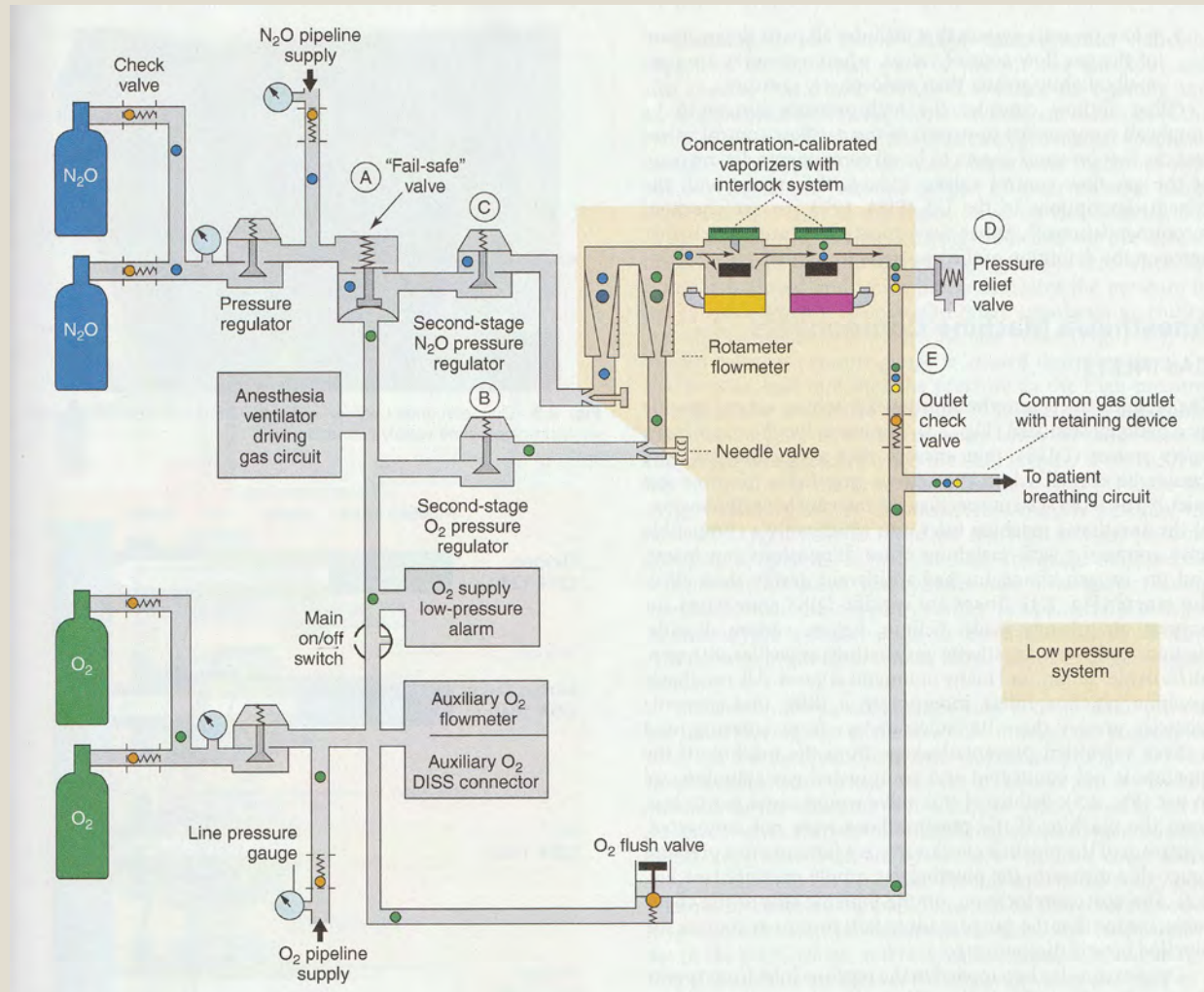


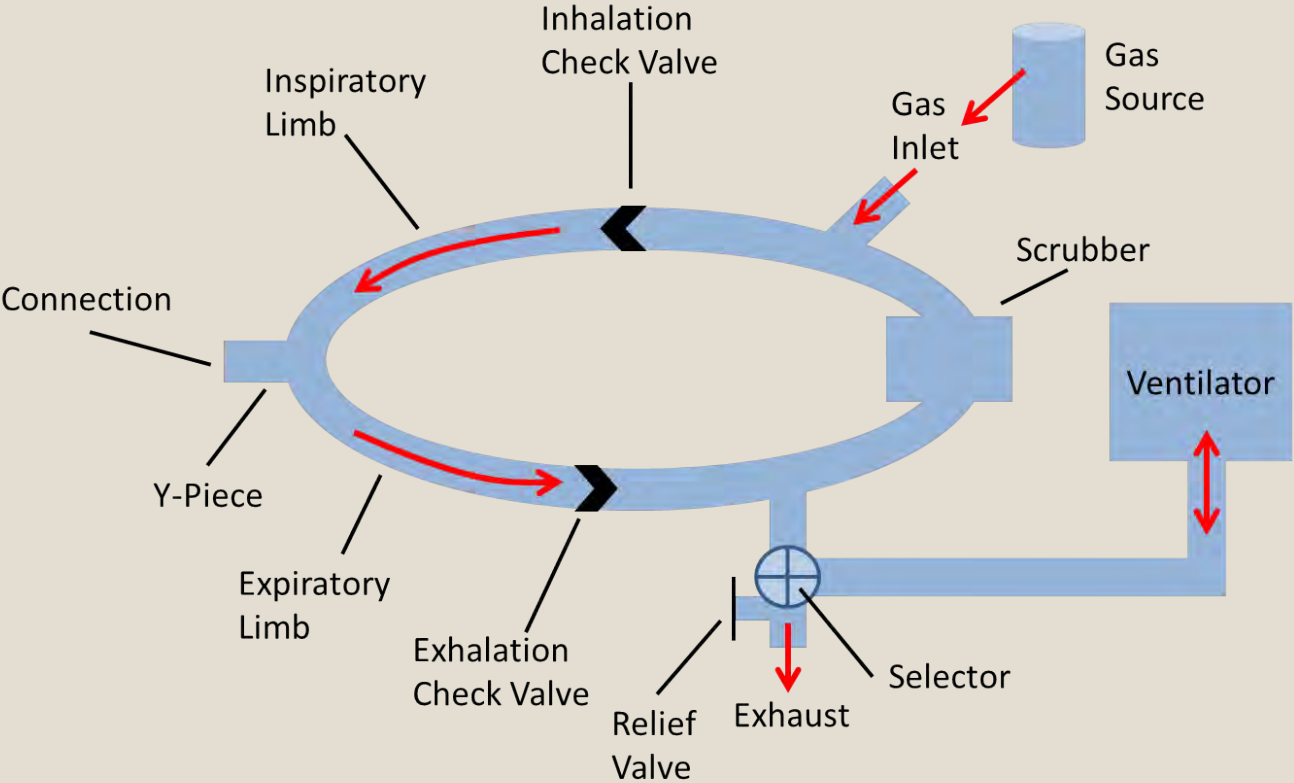
Fig 2 Connector of common gas outlet of an anesthesia machine. [muhadharaty.com](http://muhadharaty.com)



# The breathing circuit

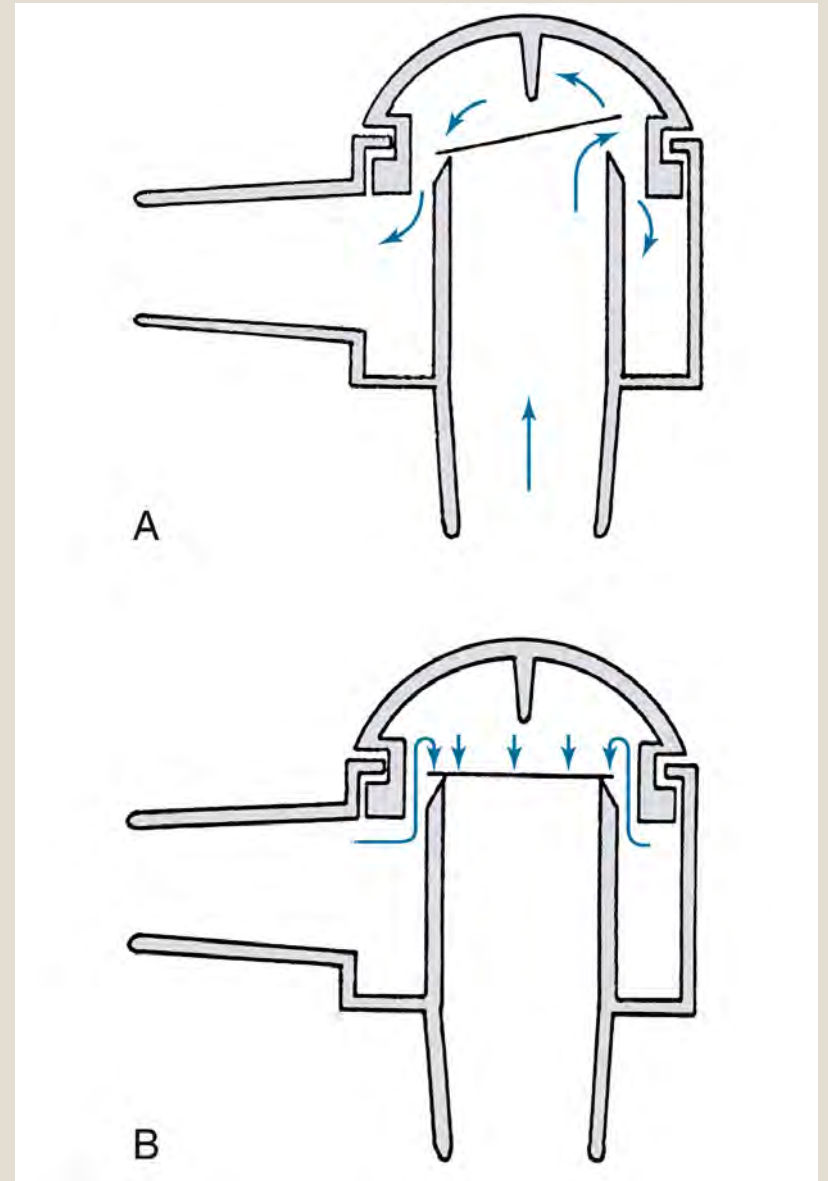
- Low resistance
- Minimal re-breathing
- Removal of carbon dioxide
- Gas composition changes
- Warmed humidification
- Disposal of waste gases

# Chemical absorption of carbon dioxide

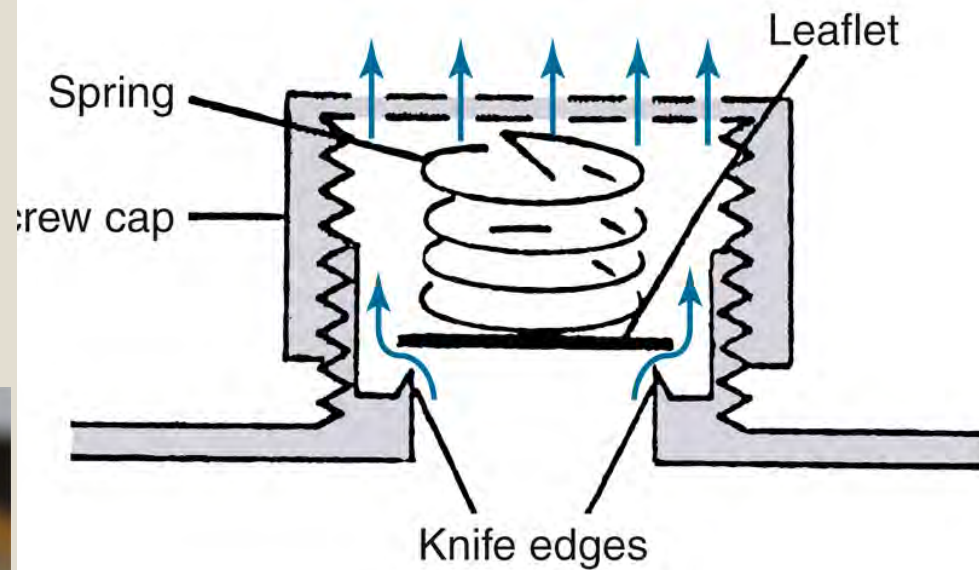


# Unidirectional valves

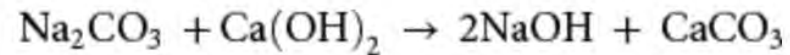
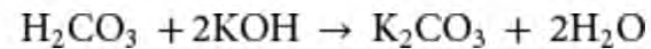
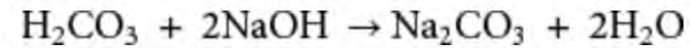
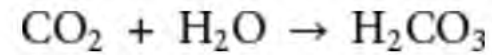
- Inspiratory valve
- Expiratory valve



# Pop-off valve



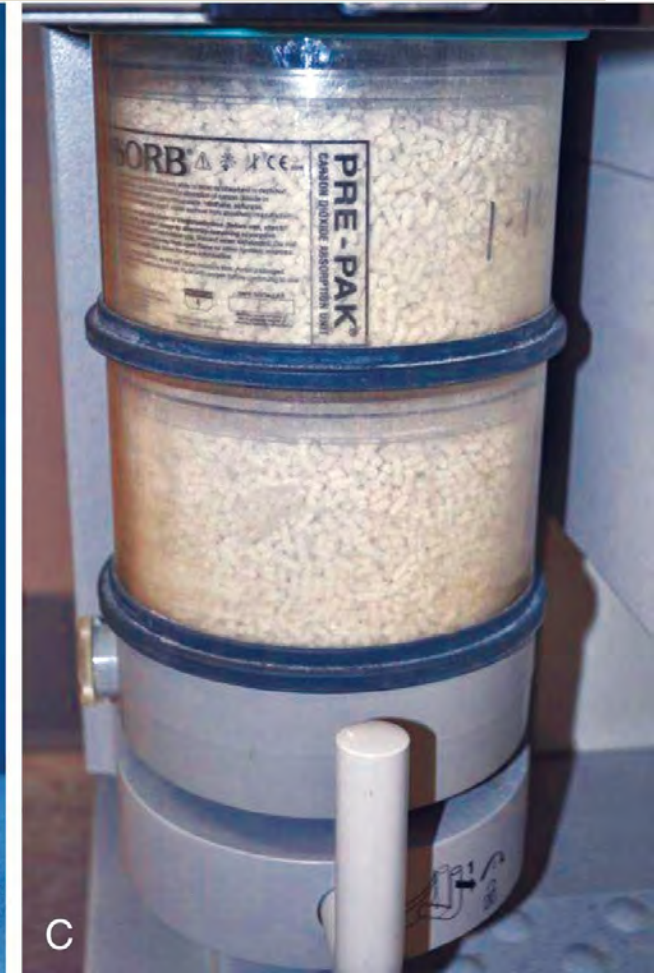
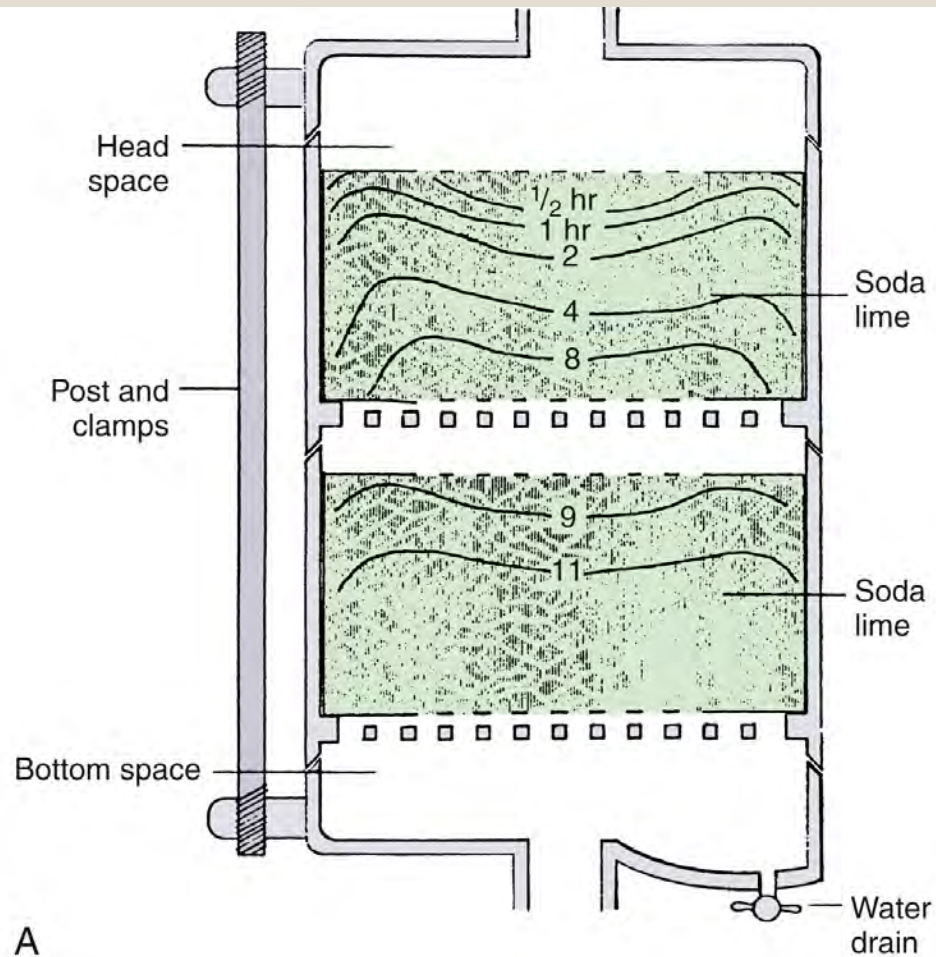
# Carbon dioxide absorption



(or  $\text{K}_2\text{CO}_3$ ) (or  $2\text{KOH}$ )

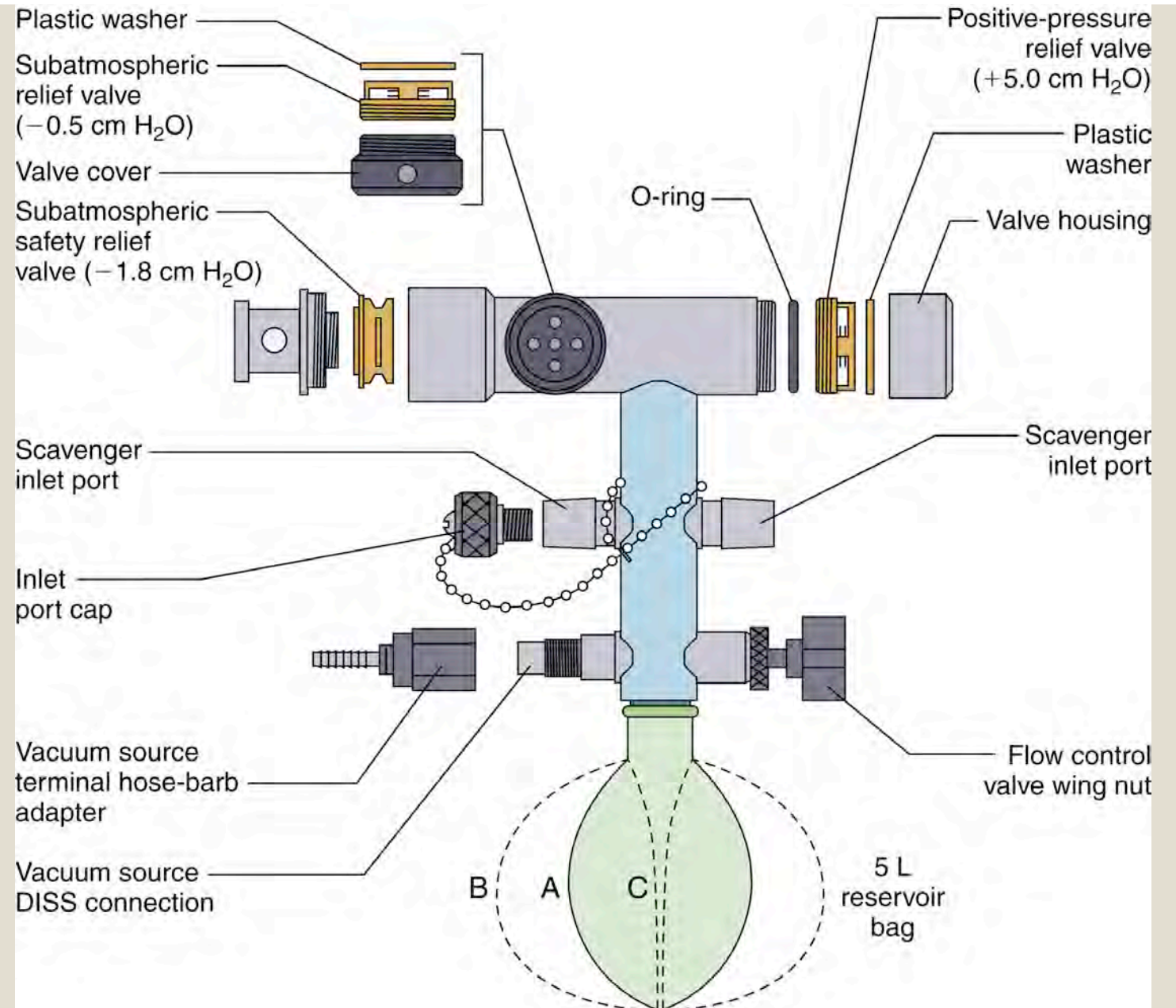


# Carbon dioxide absorbent mesh size and channeling

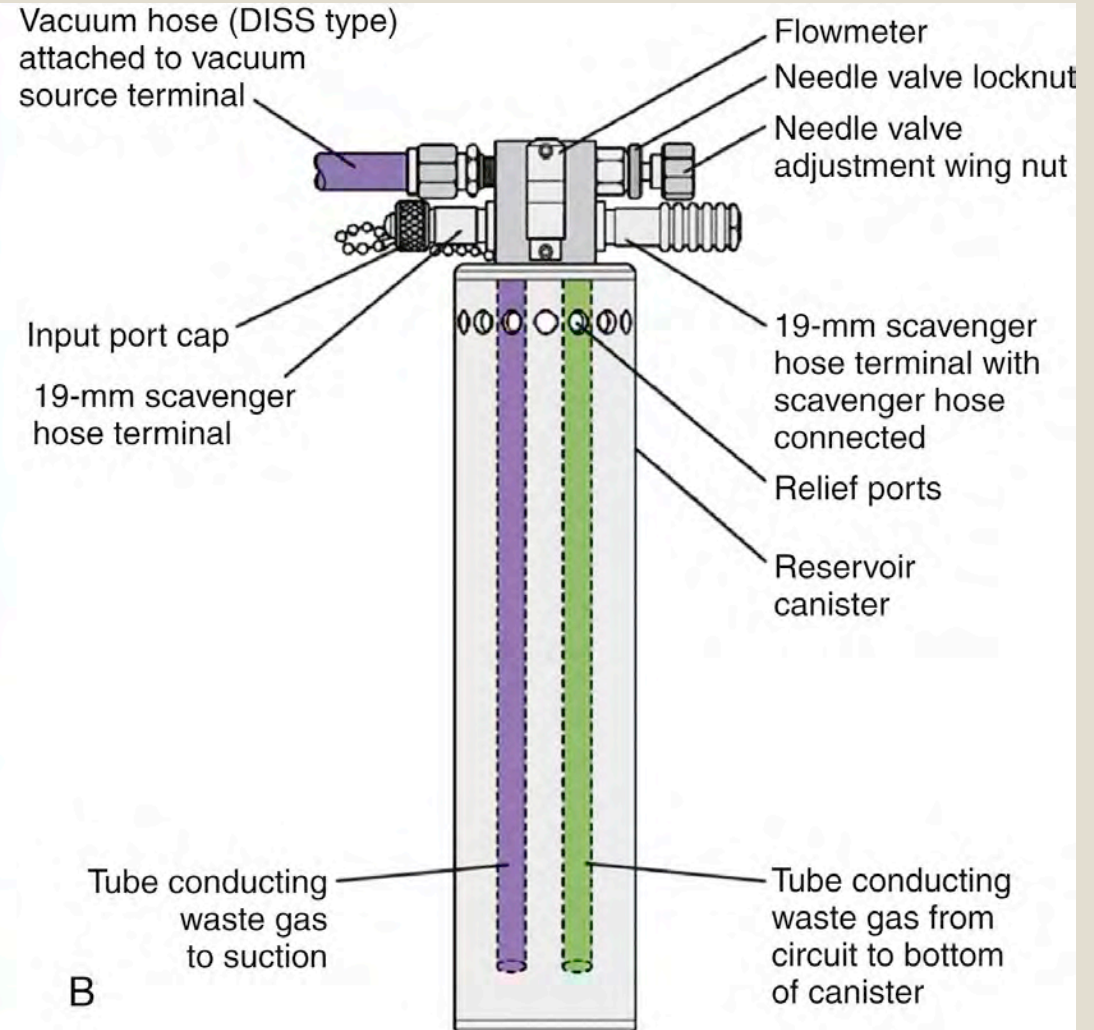
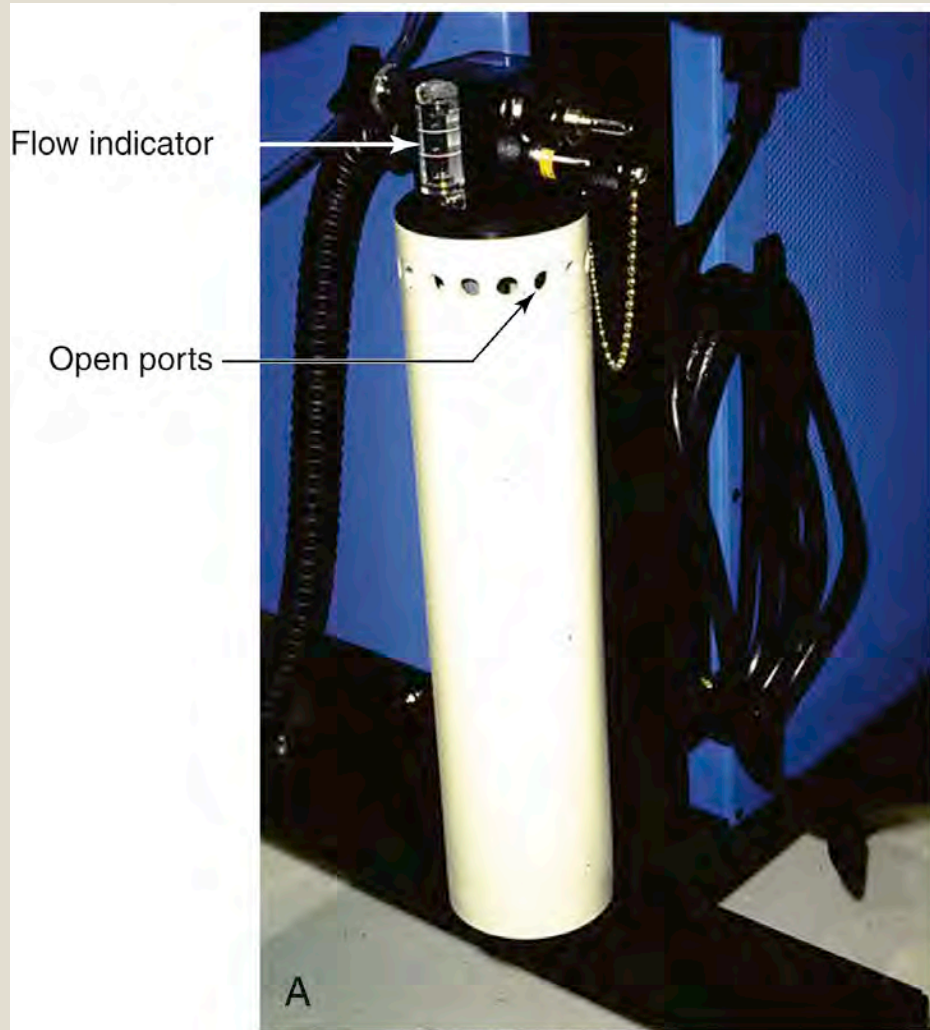


# Scavenging Interface

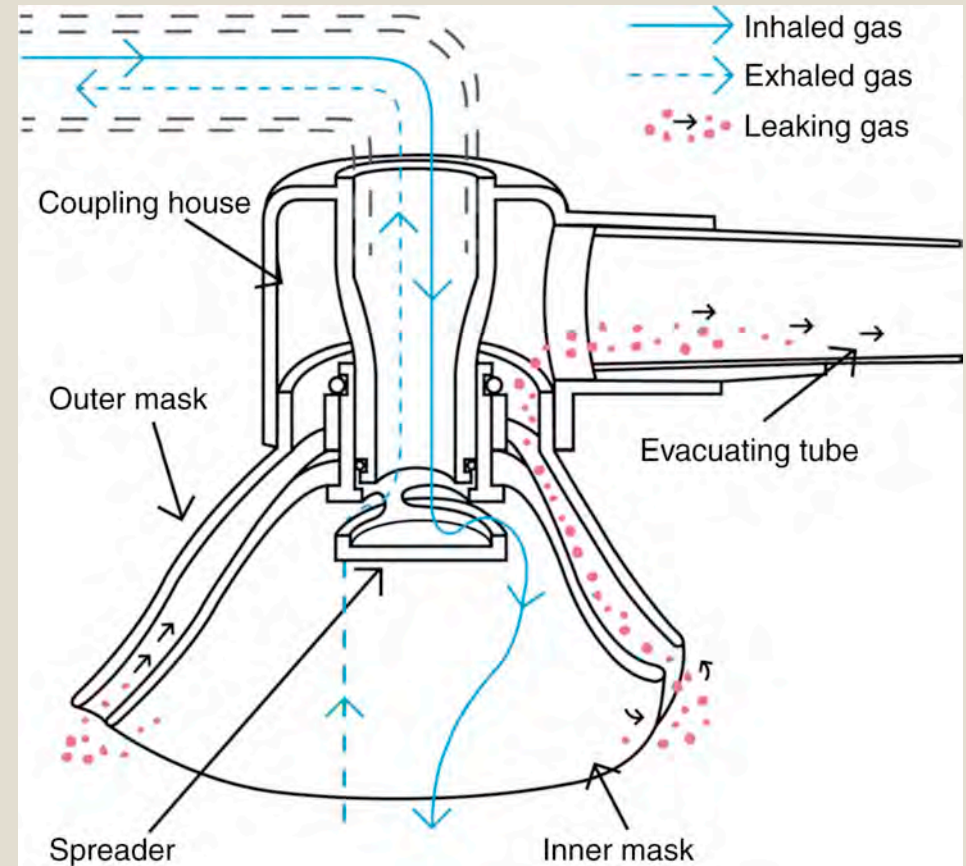
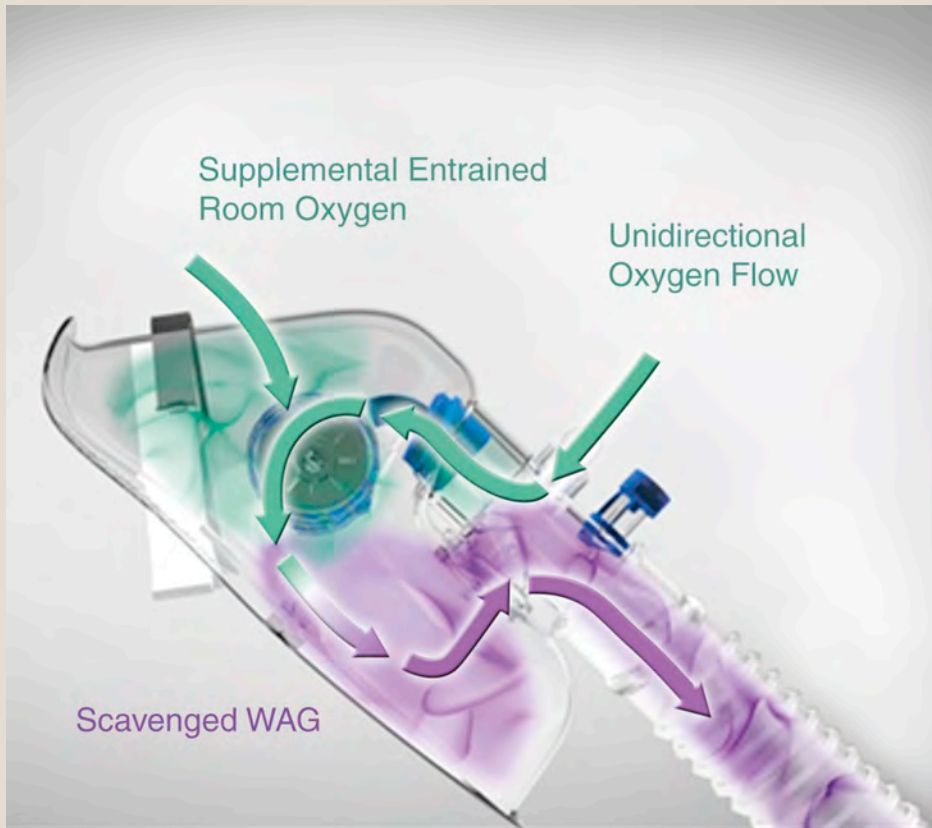
- Open
- Closed



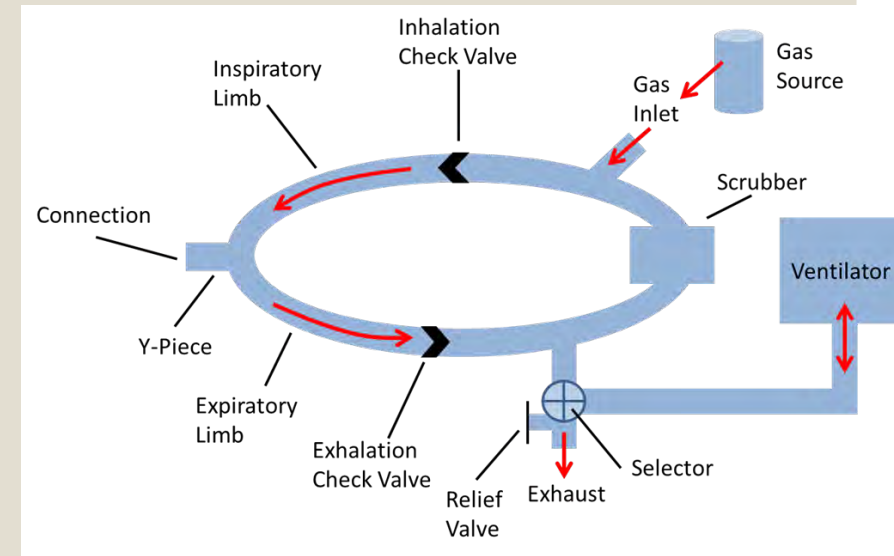
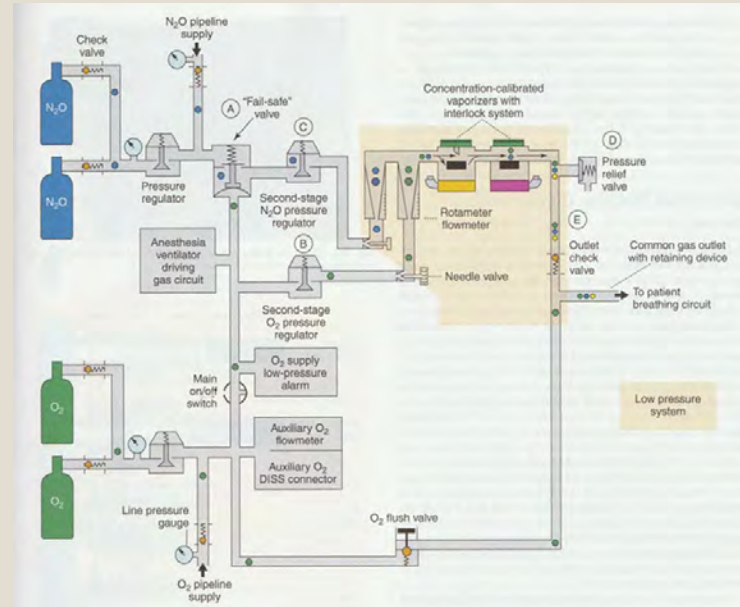
# Open Reservoir scavenging system



# Post anesthesia care unit



# Anesthesia Machine



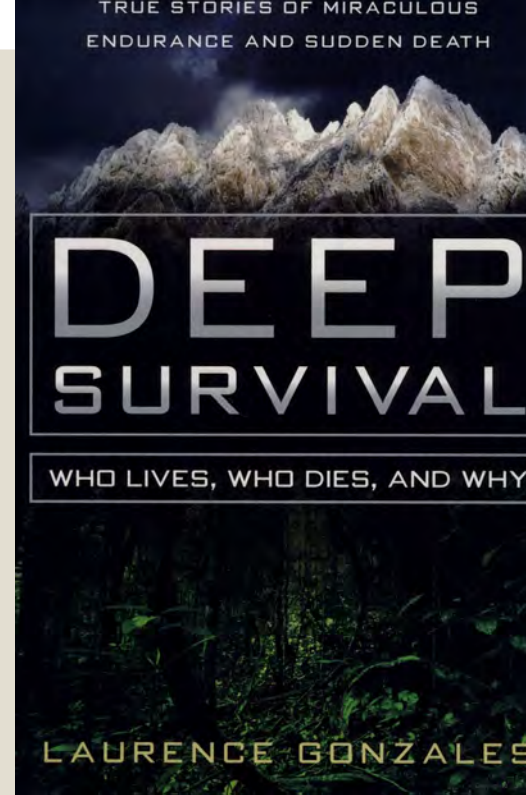
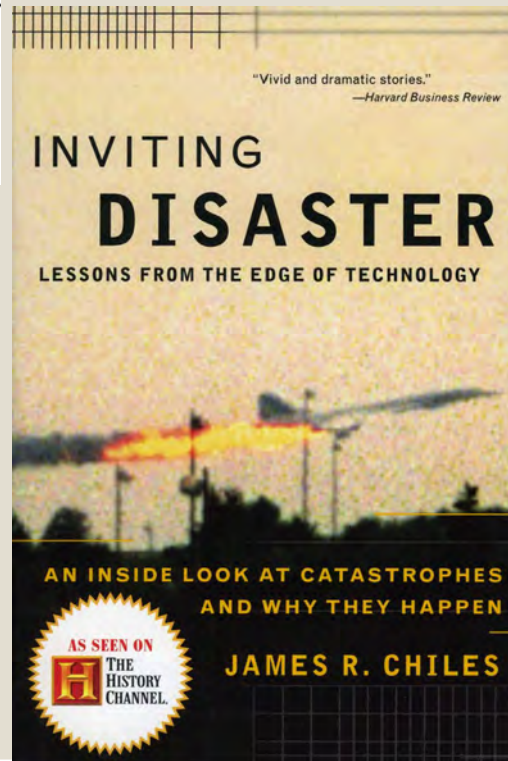
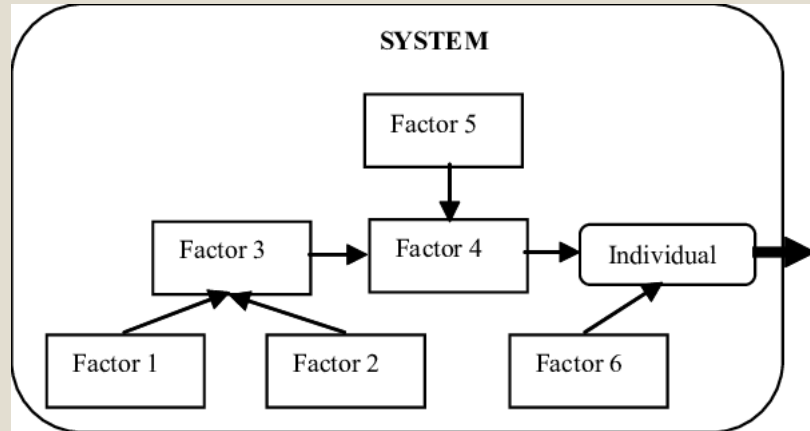
# Risk management

- Define potential problems
- Estimate the likelihood of occurrence
- Weight the relative benefits of expending available resources
- Apply solutions
- Monitor

# Incidence

- ASA Closed claims database
  - 115 in 6000 for gas delivery systems
  - 0.23-0.4%

# Chain of events





# Aggravating factors

- Failure to check equipment
- Lack of familiarity with equipment
- Inexperience
- Haste
- Inattention
- Distraction
- Fatigue

# Response



# Capnography

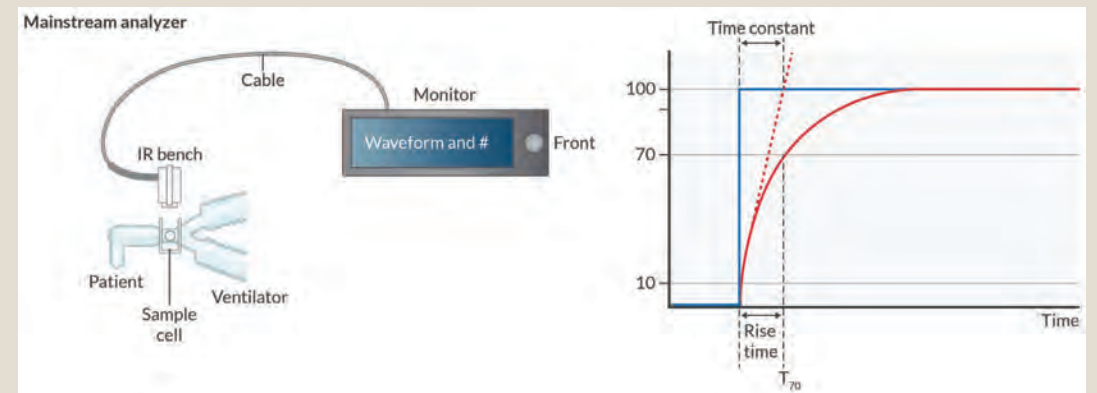
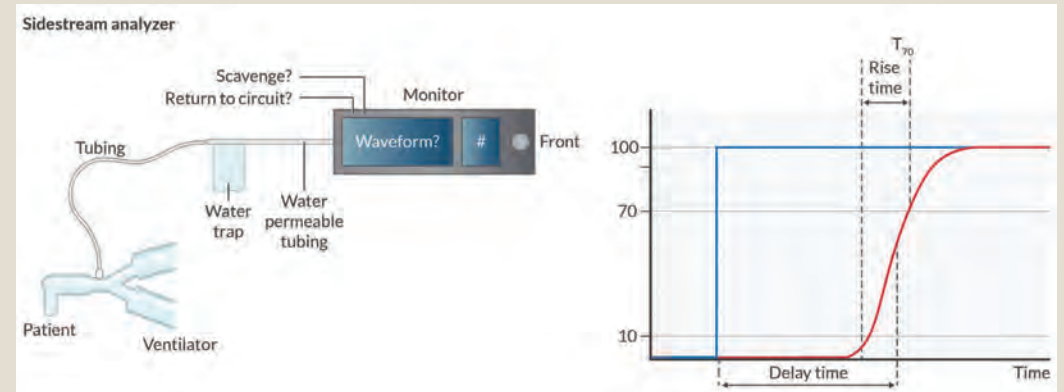
There are two primary methods

A sidestream (or diverting) system aspirates a sample from the airway and transports it to an external monitor

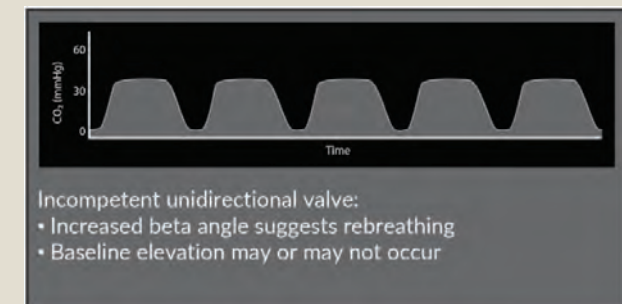
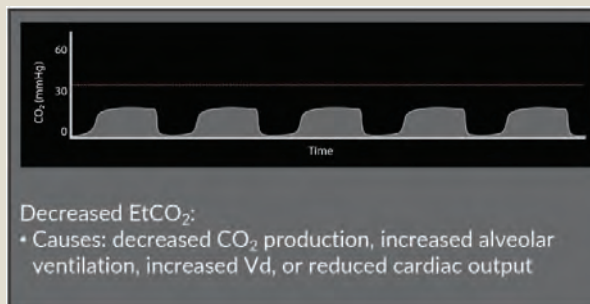
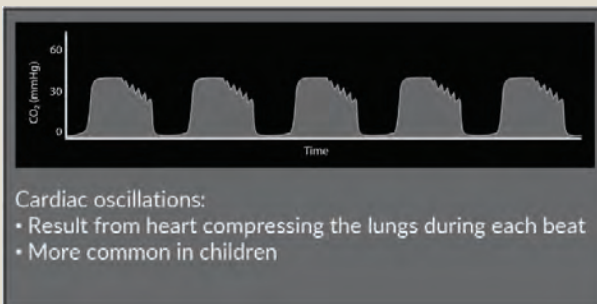
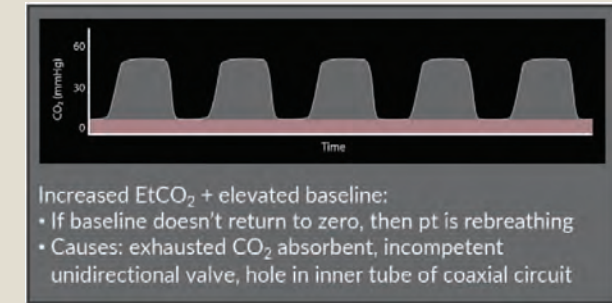
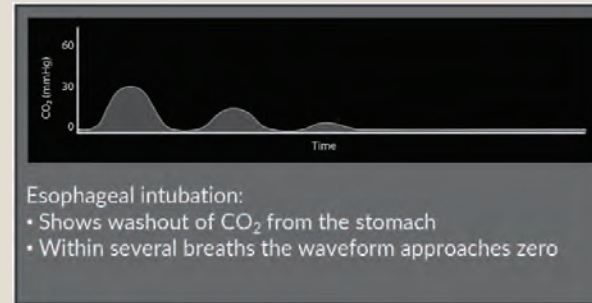
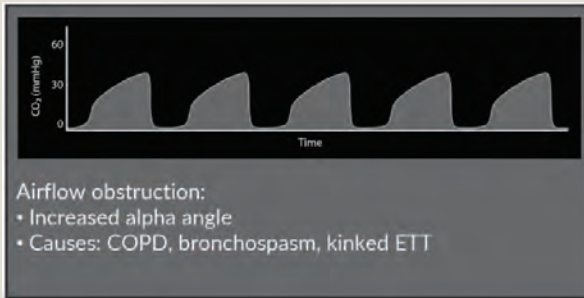
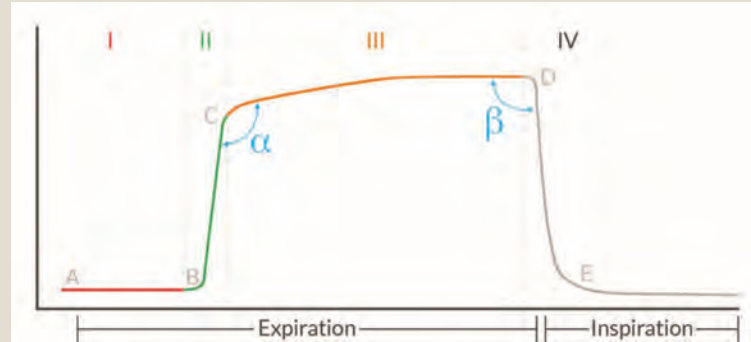
- Located external to the airway, and it requires a sampling line to continuously aspirate gas from the airway

By contrast, a mainstream (or non-diverting) device is placed directly inside the airway







- An adapter is placed between the patient's airway and the breathing circuit which adds apparatus dead space



# Capnography Waveforms



# Measurements of EBL

Percentage of Saturation		
%	50%	50%
nL	 6 mL	 6 mL
mL	 50 mL	 75 mL
mL	 80 mL	 120 mL



The most common method of assessing blood loss relies on visual inspection of the suction canisters, sponges, surgical drapes, gowns, and the floor. Although visual estimation is the standard of care, such subjective assessments varying greatly from one provider to another, and are complicated by irrigation solutions, body fluids, body tissues that may be incorporated into a blood/tissue matrix, and intravascular volume issues such as hemodilution and hemoconcentration.

# Measurements of EBL

With the Triton app you take a picture of blood-soaked sponges or a suction canister filled with blood, and then the app pushes this data to a cloud server. Here, the Triton system uses computer vision algorithms and machine learning to analyze the photographic and geometric information about the hemoglobin mass shown in the image. Finally, the server transmits the data back to the operating room, giving you a highly reliable, real-time assessment of blood loss. The entire process is completed in a matter of seconds.



# Non-Invasive Hemoglobin monitoring

Non-invasive hemoglobin monitors

The technology emits multiple wavelengths of light and then calculates the hemoglobin concentration based on the adsorption of light in the blood [12]. The device uses a finger tip probe similar to a standard pulse oximeter sensor and determines the hemoglobin noninvasively.



